

Sharp Tools for Optimising Navigation Sensor Arrays

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Sharp Tools for Optimising Navigation Sensor Arrays

■ Synopsis

- What's the problem
- What are the sharp tools
- The math in a nutshell
- Gulf of Mexico bottom positioning example
- NW Europe Loran Chain optimal station locations example

Sharp Tools for Optimising Navigation Sensor Arrays

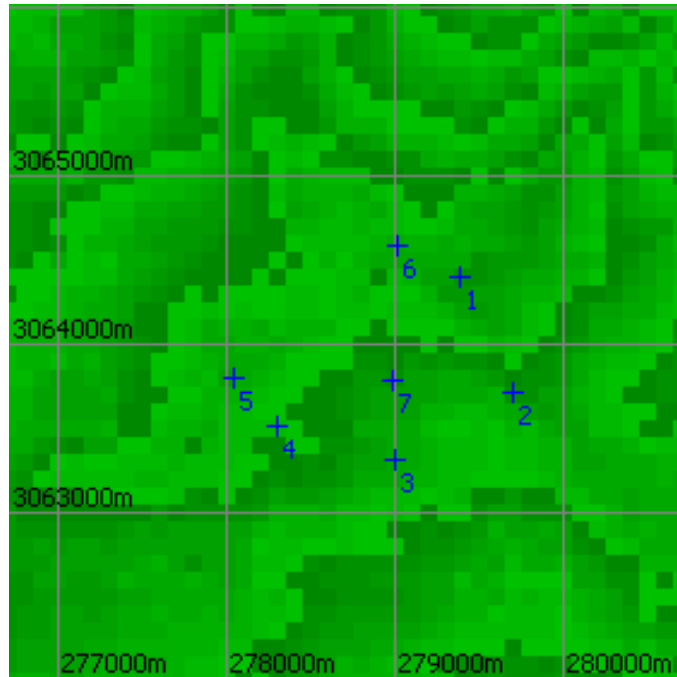
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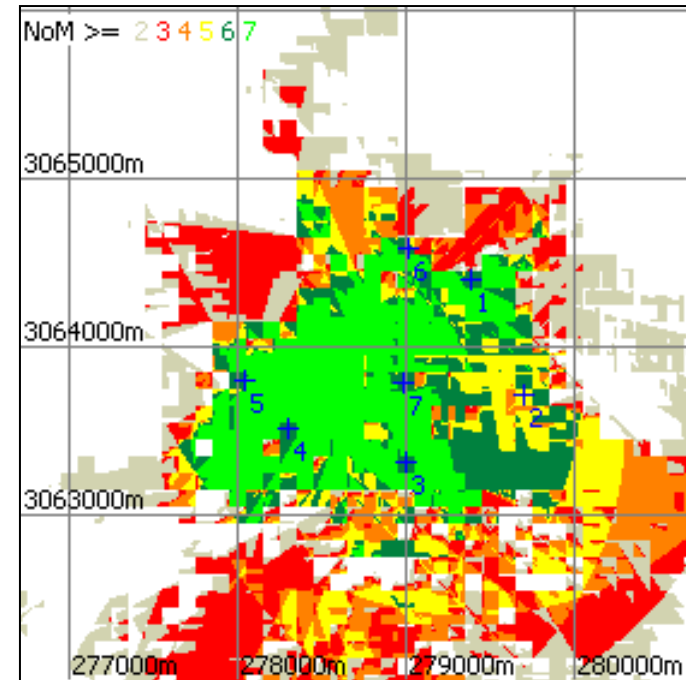
■ Emeritus Solutions' Expertise

- Technical Consultancy
- Navigation Solutions : Algorithms and Analysis
- Underwater Acoustics : Algorithms, Analysis & Materiel
- Digital Signal Processing : Algorithms and Mechanisation
- Computer Systems and Software Tools
- System Development and Verification

Gulf of Mexico : Near Bottom Positioning

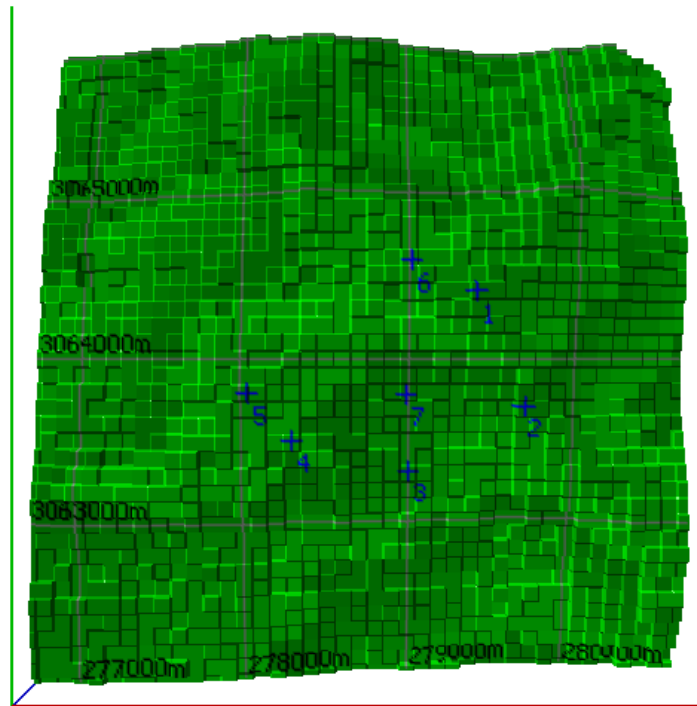


Bathymetry

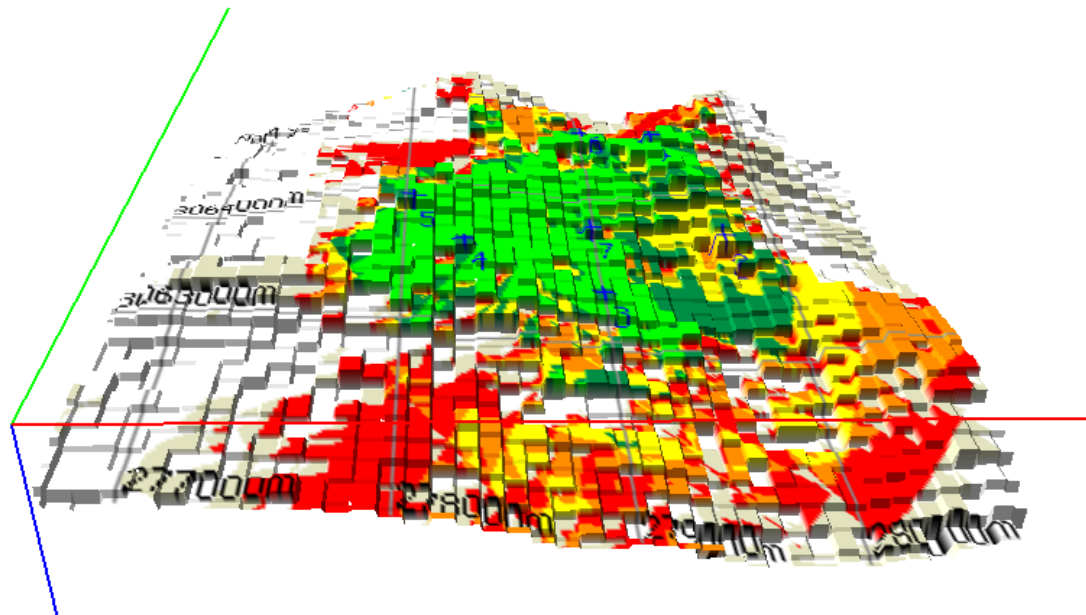


Stations in View

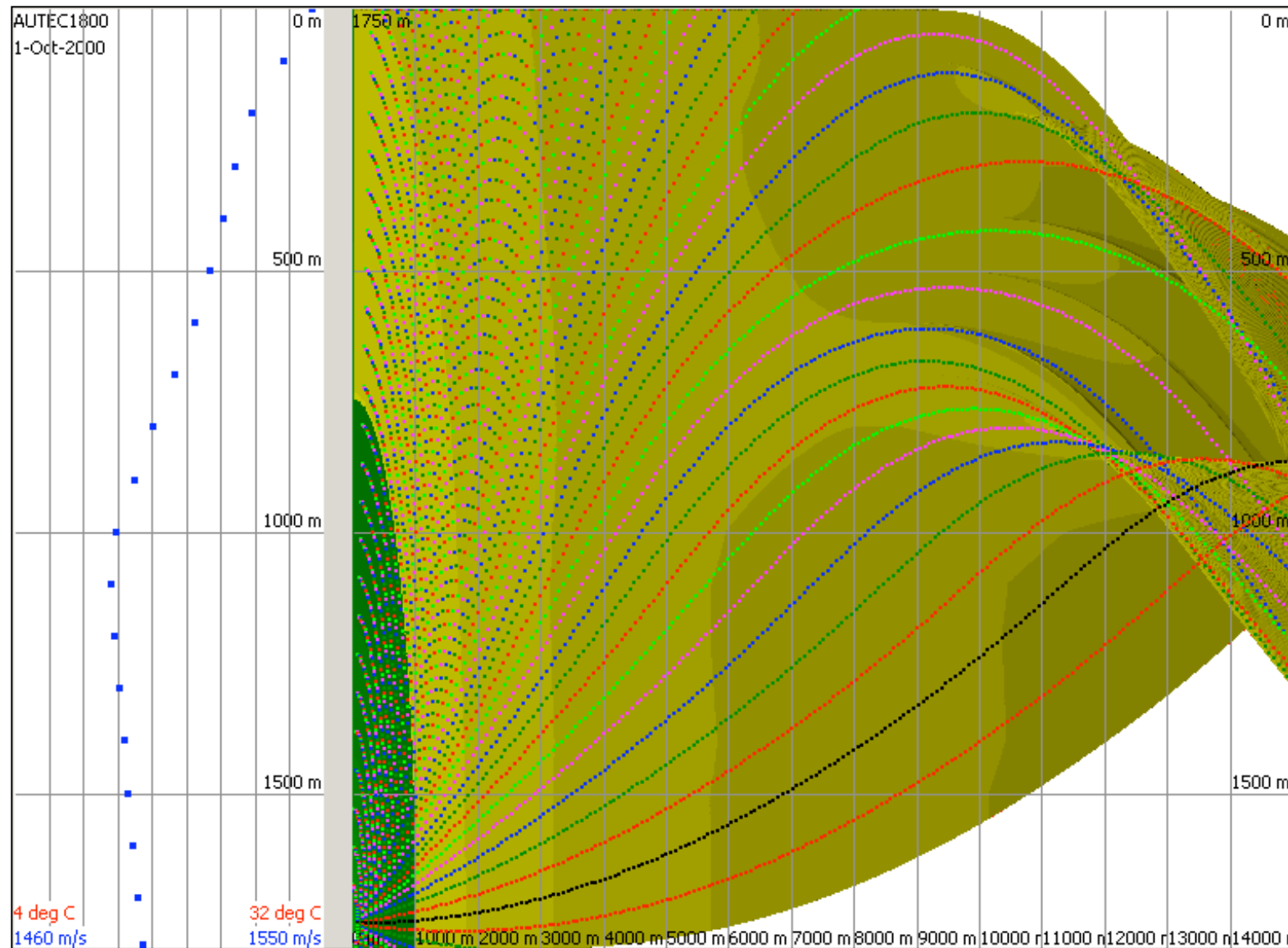
Gulf of Mexico : Bathymetry



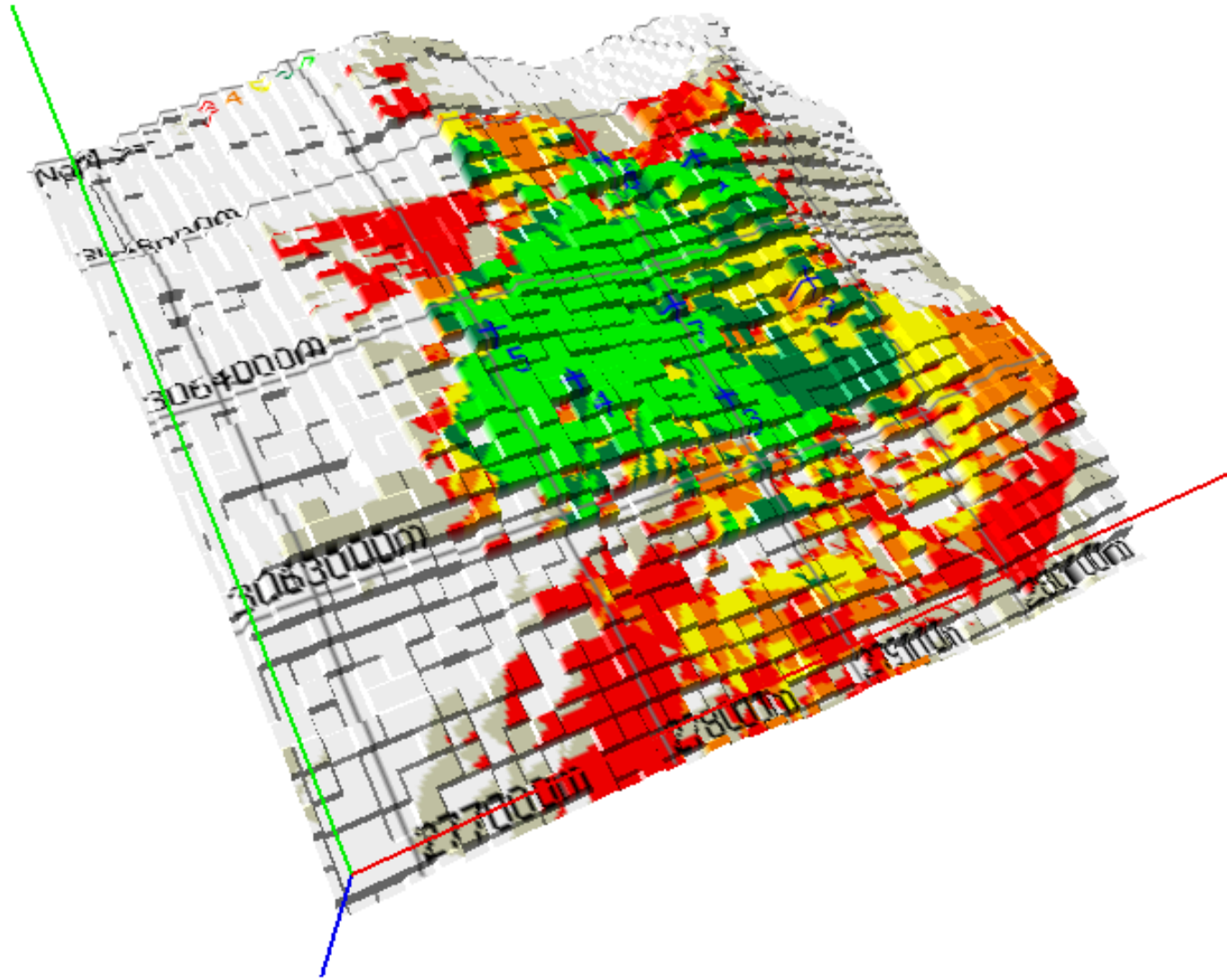
Gulf of Mexico : NoM



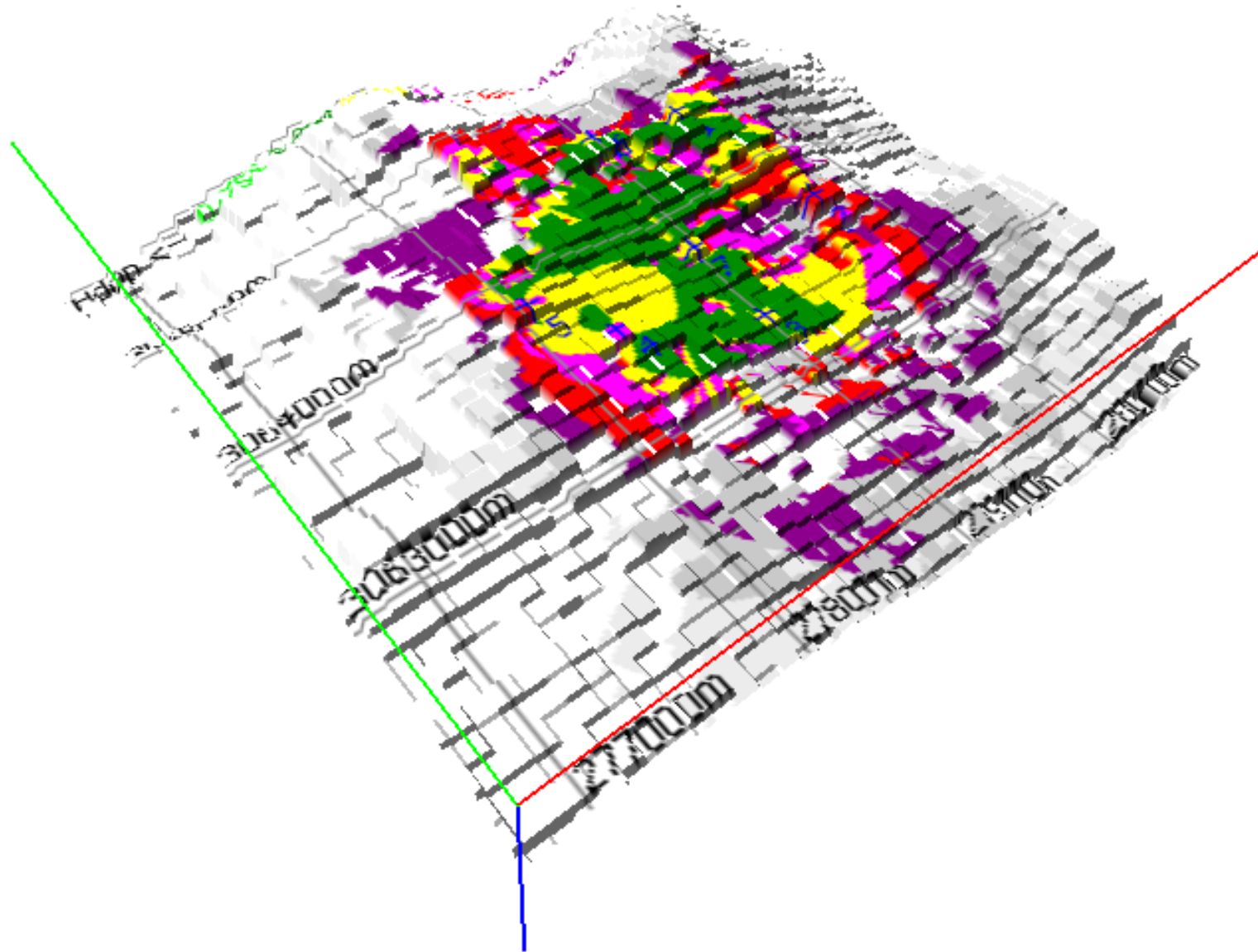
Gulf of Mexico : Sound Propagation



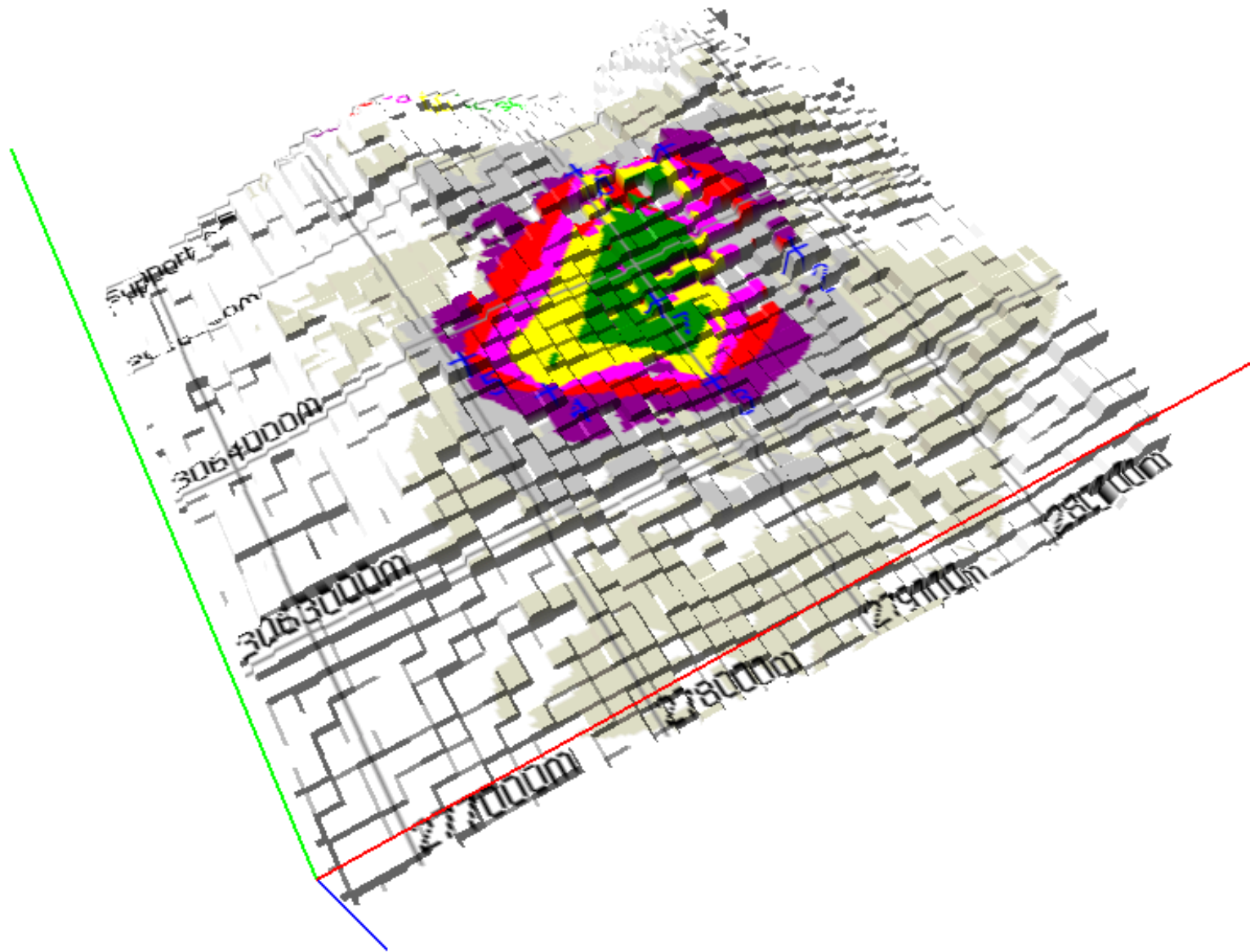
Gulf of Mexico : 3-D Depth and Coverage



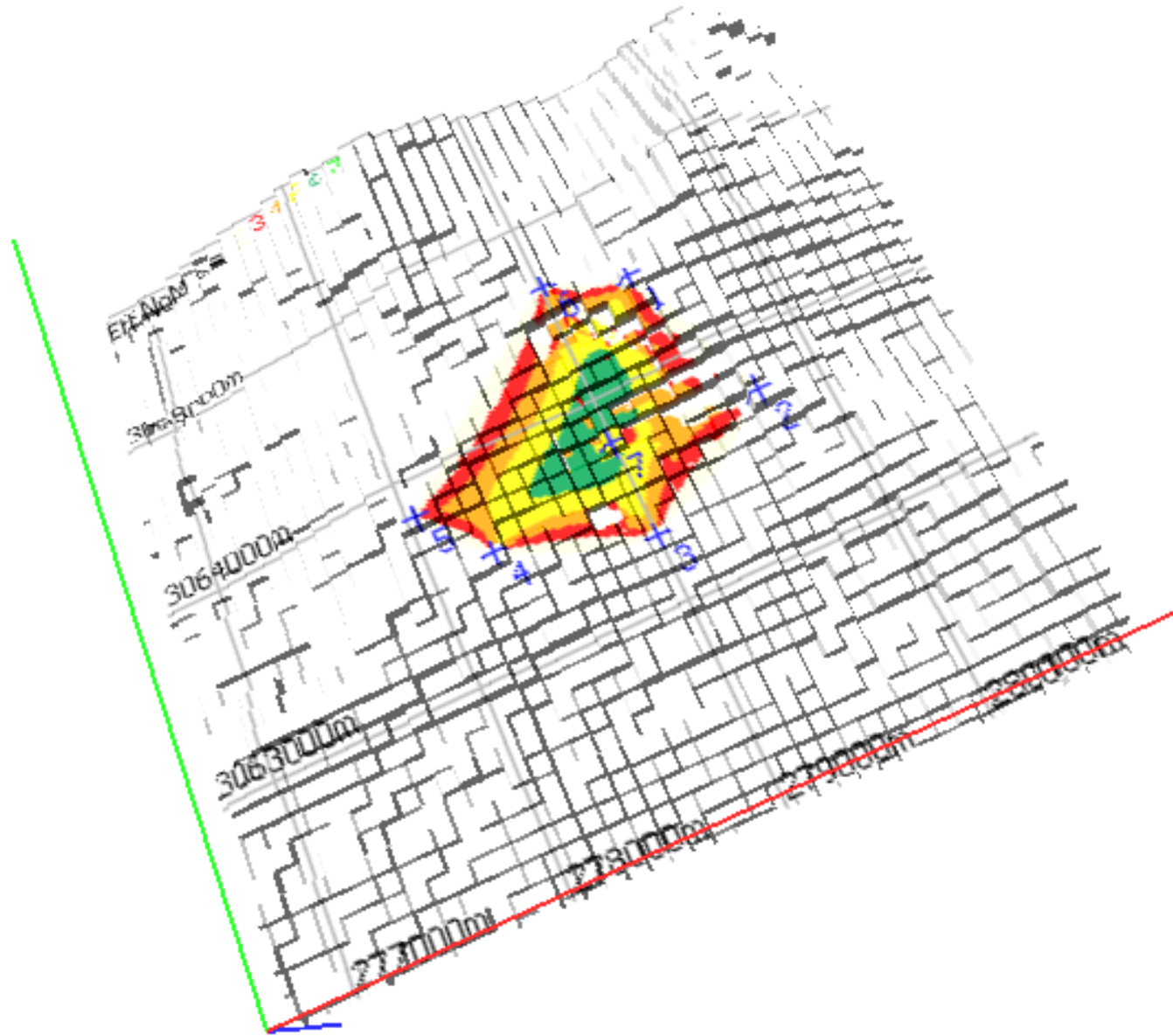
Gulf of Mexico : H dop



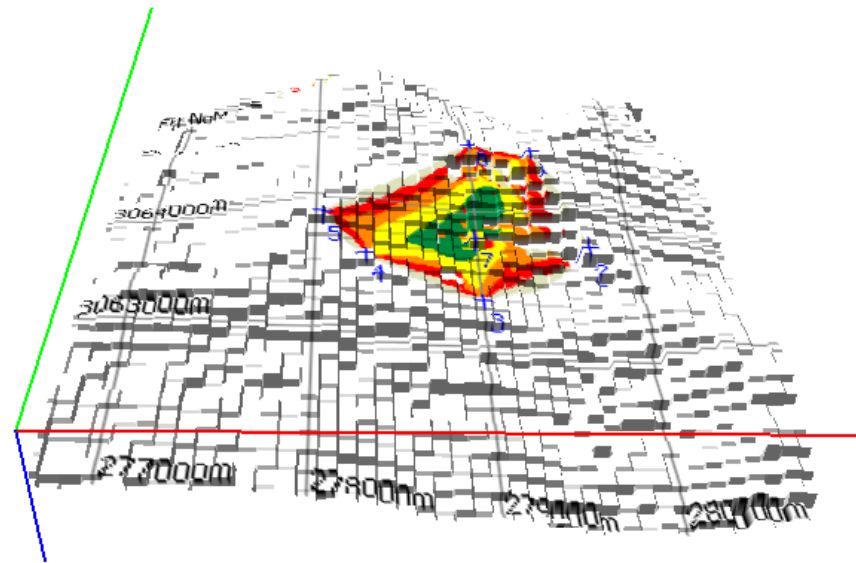
Gulf of Mexico : Support



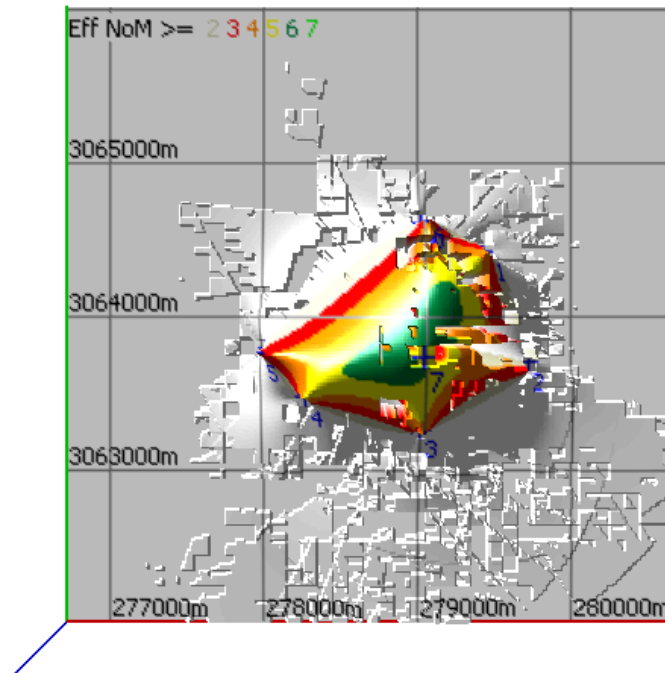
Gulf of Mexico : N eff



Gulf of Mexico : N eff



Gulf of Mexico : N eff



The Math in a Nutshell

$\underline{h}_i = [r_i : 1]^T$: augmented direction cosines

$\underline{H} = [\underline{h}_1 \dots \underline{h}_n]^T$

$$\text{cov}(\theta) = \sigma_r^2 (\underline{H} \underline{H}^T)^{-1} = \begin{bmatrix} \sigma_{xx}^2 & \cdot & \cdot & \cdot \\ \cdot & \sigma_{yy}^2 & \cdot & \cdot \\ \cdot & \cdot & \sigma_{zz}^2 & \cdot \\ \cdot & \cdot & \cdot & \sigma_{tt}^2 \end{bmatrix}$$

$$Hdop = \sqrt{(\underline{H}^T \underline{H})^{-1}_{xx} + (\underline{H}^T \underline{H})^{-1}_{yy}} = \sqrt{(\sigma_{xx}^2 + \sigma_{yy}^2) / \sigma_r^2}$$

$$Gdop = \sqrt{(\underline{H}^T \underline{H})^{-1}_{xx} + (\underline{H}^T \underline{H})^{-1}_{yy} + (\underline{H}^T \underline{H})^{-1}_{zz} + (\underline{H}^T \underline{H})^{-1}_{tt}} = \sqrt{(\sigma_{xx}^2 + \sigma_{yy}^2 + \sigma_{zz}^2 + \sigma_{tt}^2) / \sigma_r^2}$$

■ A relationship between Gdop and N

- $Gdop = 2 / \sqrt{N}$ -- A lower bound on Gdop for N sensors

■ Hz Support = Projected area of DCs / area of unit circle

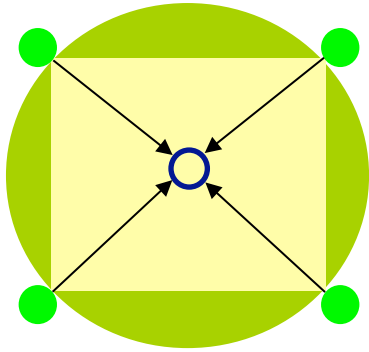
■ An expression for Tdop and Clock sensitivity

- $\ell = \sum h_j$ -- Sum of the direction cosines
- $Tdop = \sqrt{1 / (n - \ell^T M \ell)}$ -- An insightful expression for Tdop

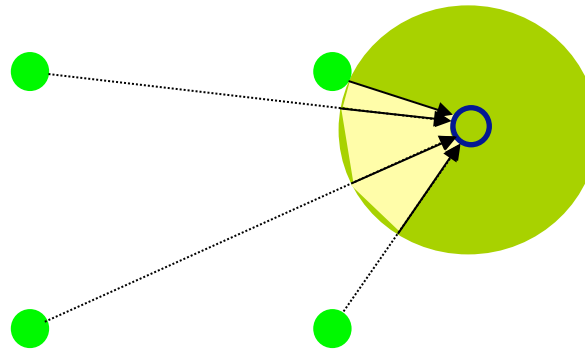
■ The Bad Geometry or Clock Penalty term

- $M_{\text{clock}} = M \ell \ell^T M / (n - \ell^T M \ell)$ -- Extra DOP due to estimating the clock

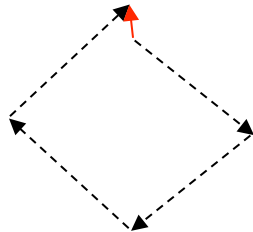
Support and Sensitivity : Graphical Examples



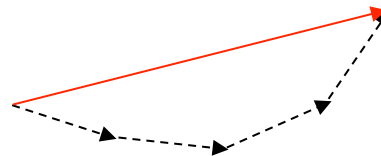
Support ~ 90%



Support ~ 20%



Neff ~ 4



Neff ~ 0

Sensitivity to clock bias, noise and speed of sound

N	DOP
7	0.756
6	0.817
5	0.894
4	1.000
3	1.155
2	1.414
1	2.000
0.25	4.000

$$\text{DOP} = 2 / \sqrt{N}$$

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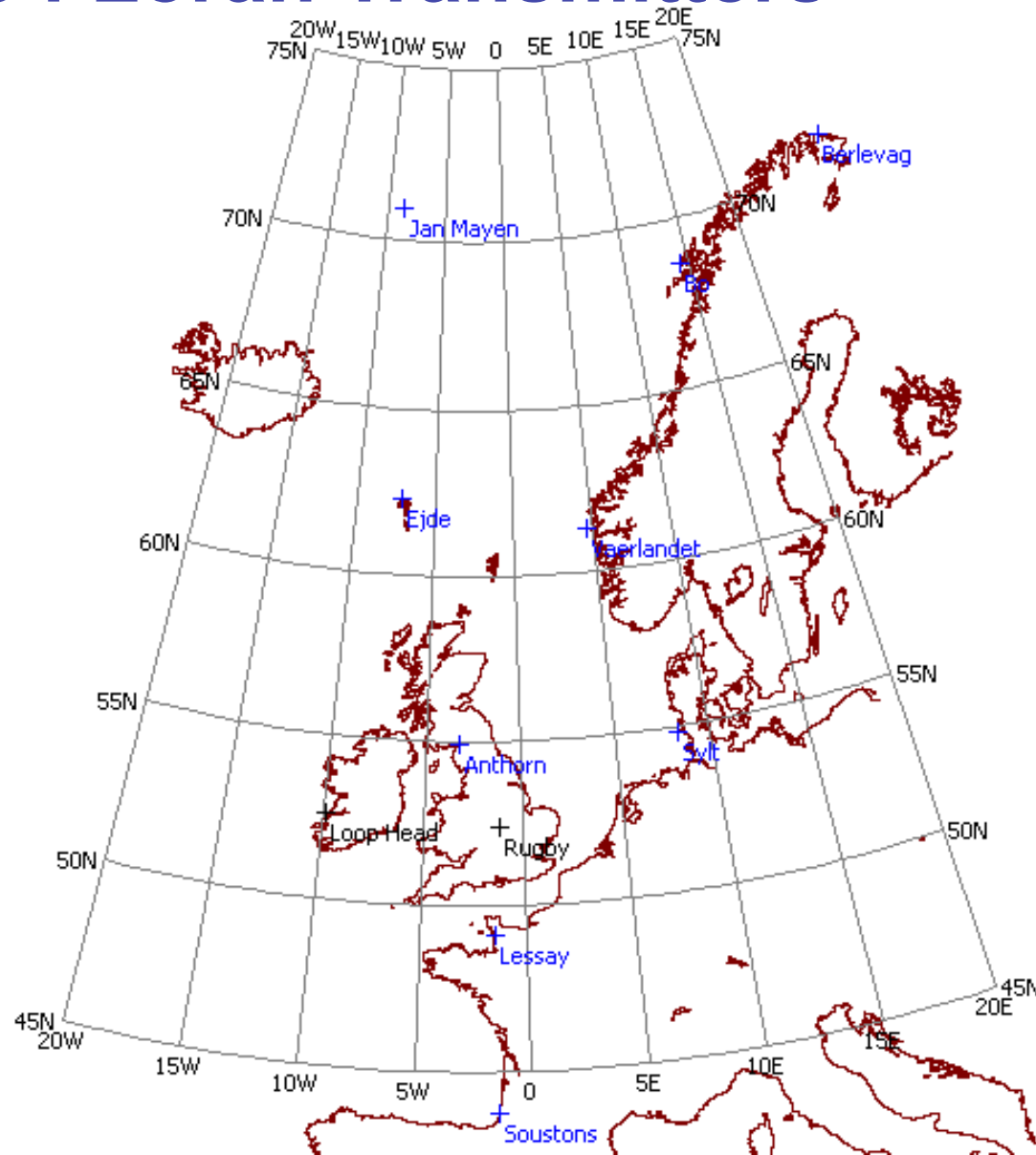
■ What are the problems with underwater positioning

- Clock performance, especially performance v power
- Propagation velocity, at best poorly known
- Multipath; Surface reverberation; Shadow zones; ...

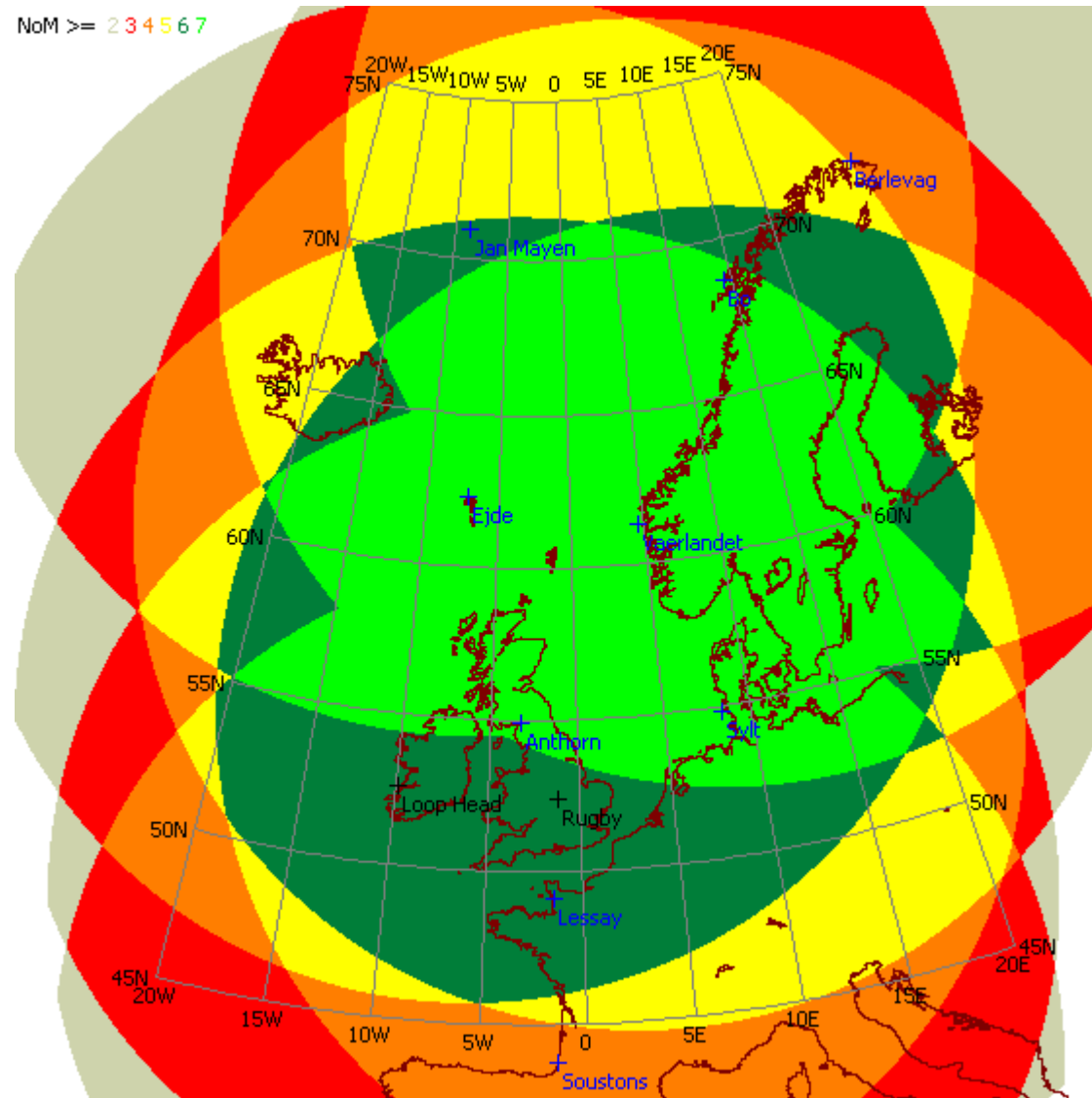
■ What are the Magic Bullets

- Working inside the array
- Using symmetric sensor arrays
- Analysing the propagation conditions
- Analysing and refining the range geometry
- Perform support / Neff / DOP analysis
- Assess, analyse and resolve second order issues
- Reviewing the slant range measurements
- Post process system data for accuracy and insight
- OpenGL / GPUs / Quaternions / Mathematics & Statistics

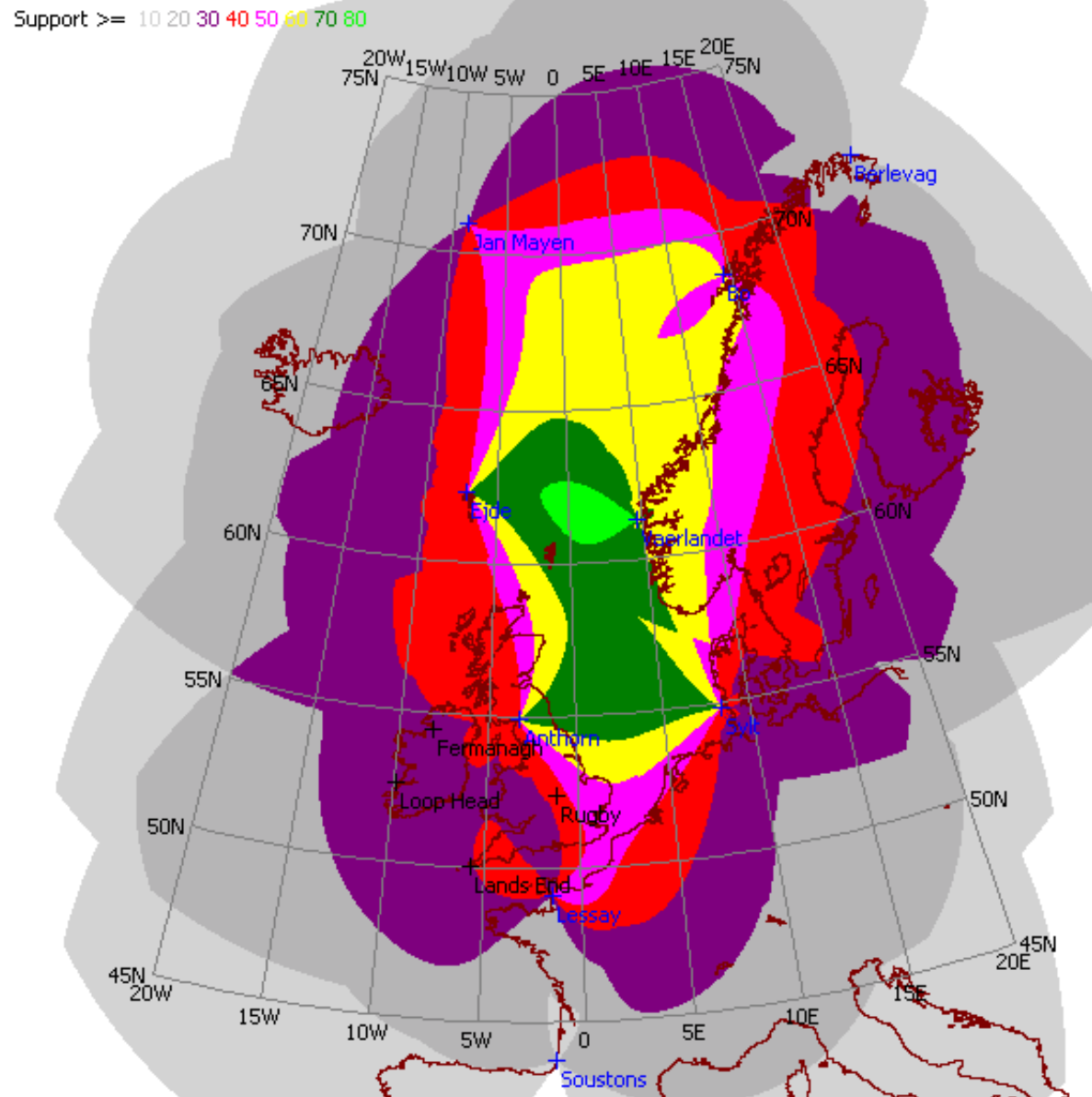
NW Europe : Loran Transmitters



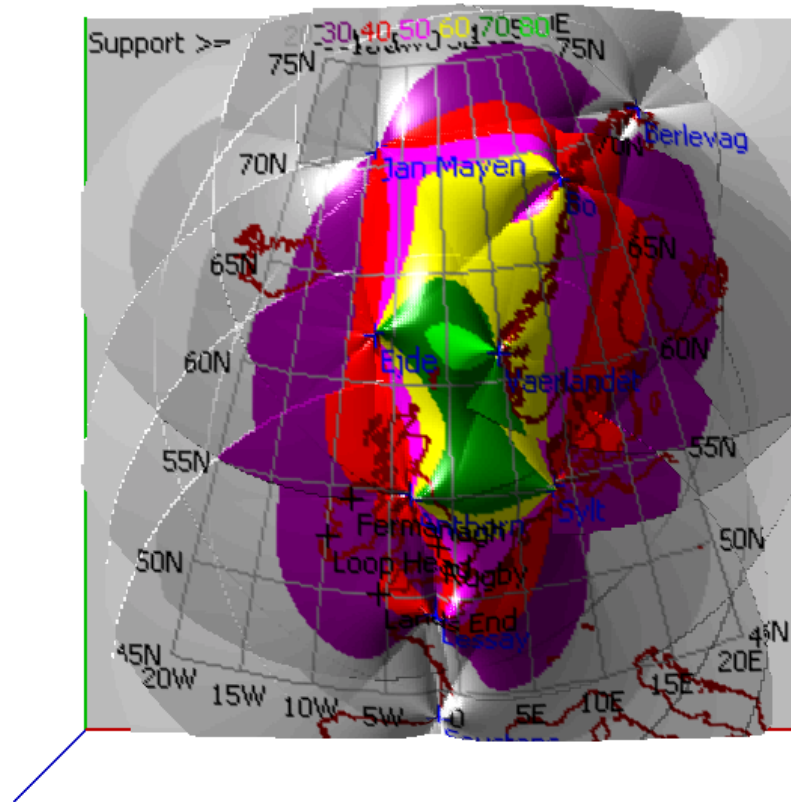
NW Europe : Loran Stations – Baseline : NoM



NW Europe Loran – Baseline : Support

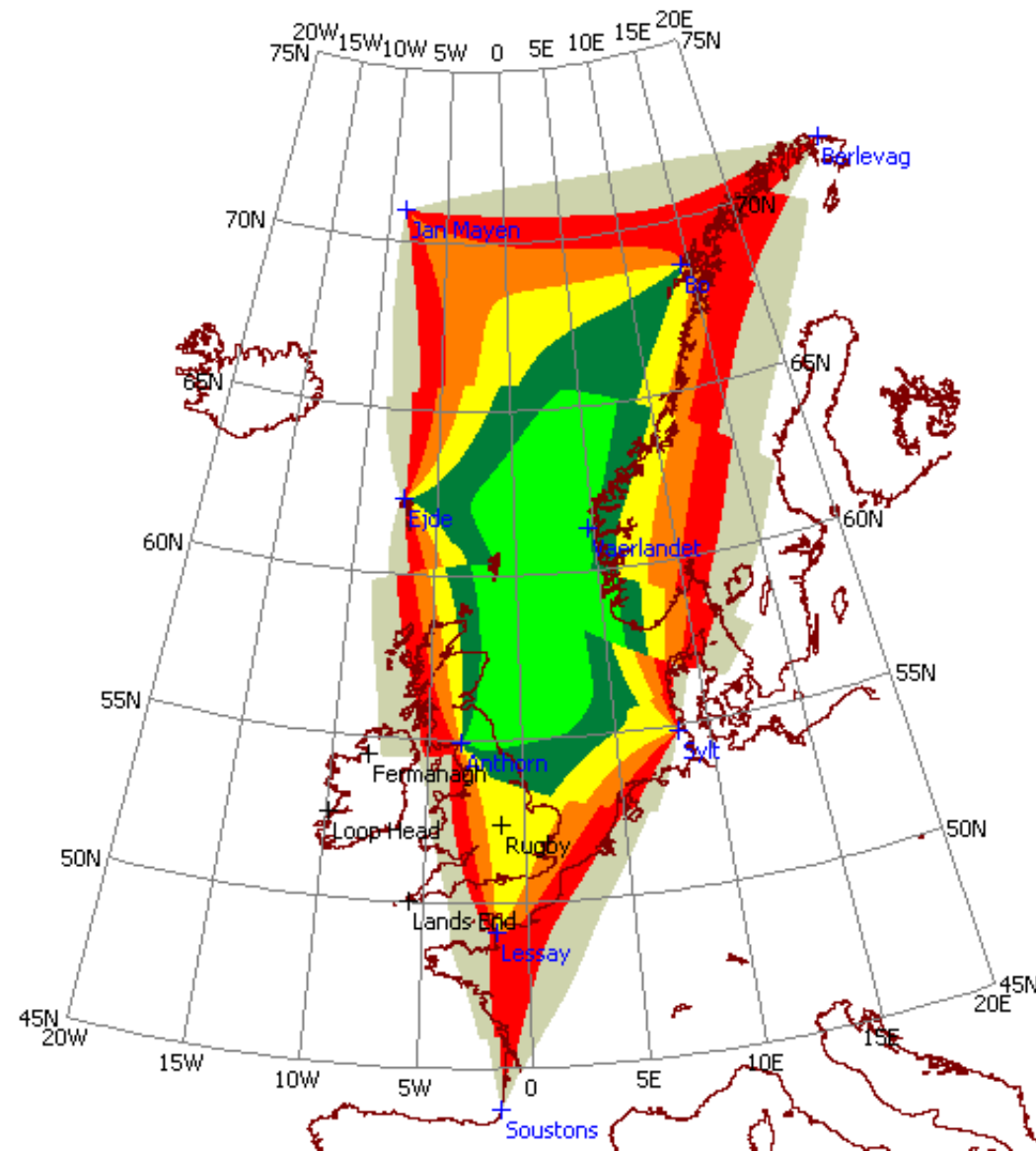


NW Europe Loran – Baseline : Support



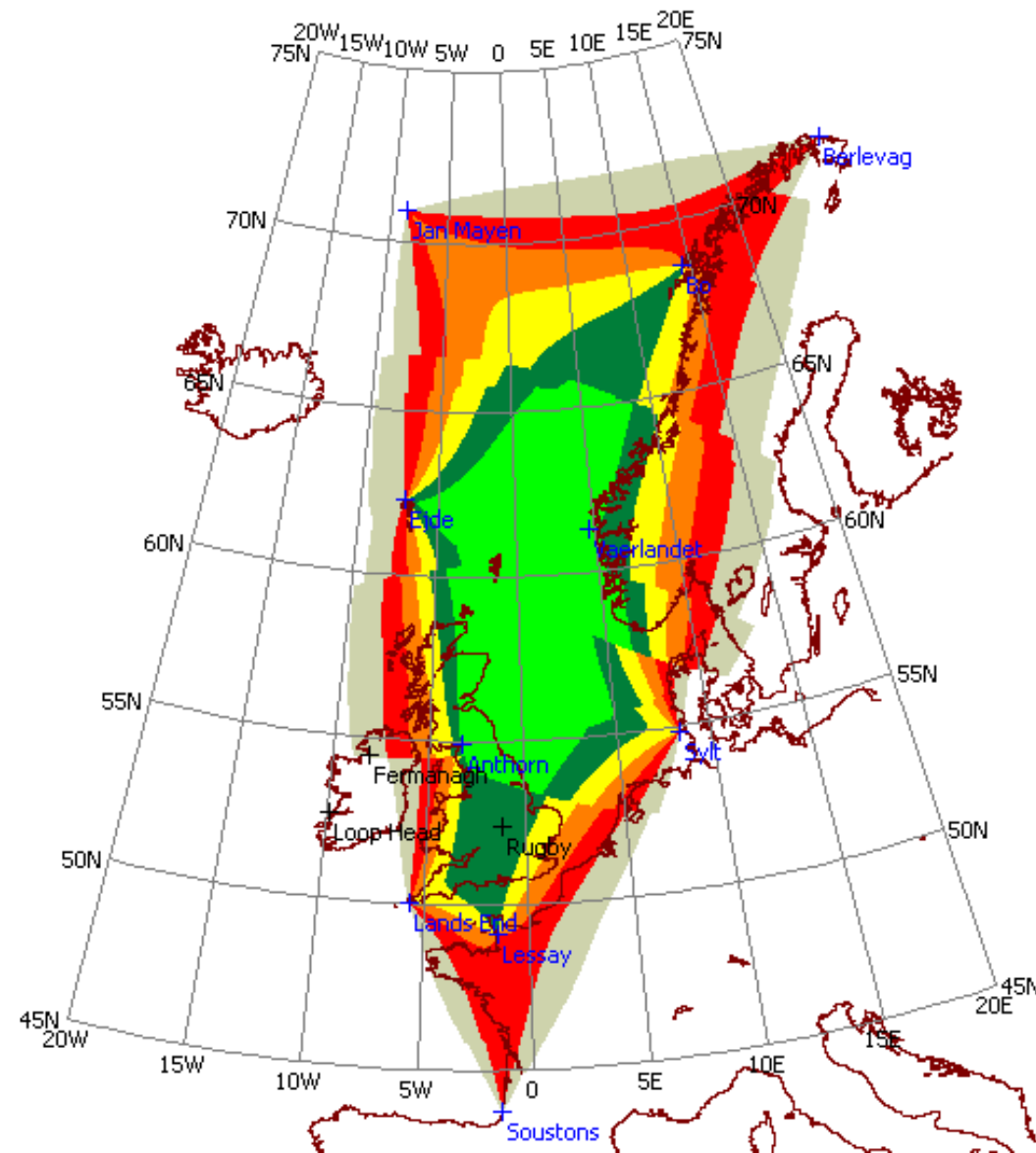
NW Europe Loran – Baseline : Neff

Eff NoM \geq 2 3 4 5 6 7



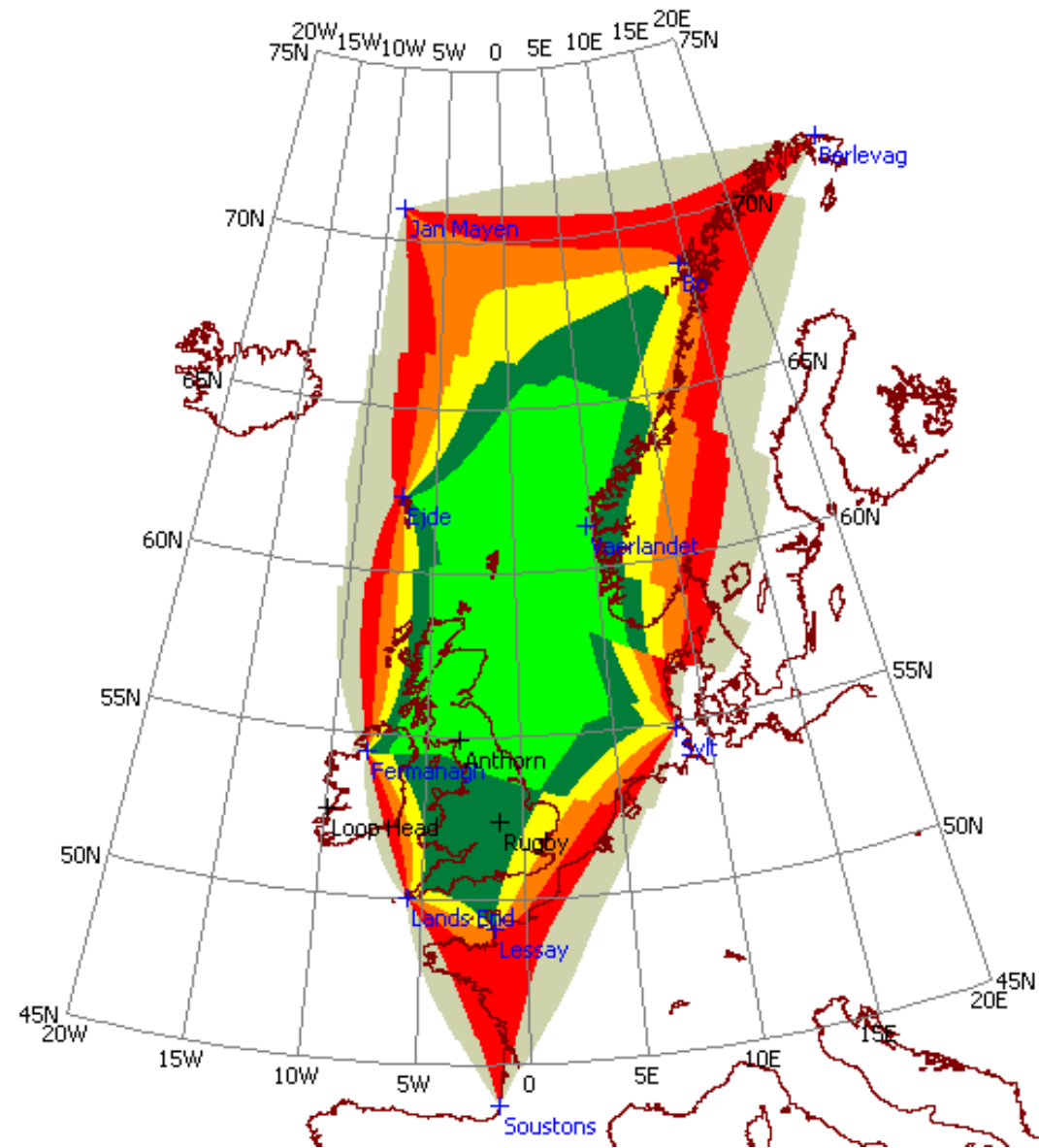
NW Europe Loran– Baseline + LE : Neff

Eff NoM \geq 2 3 4 5 6 7



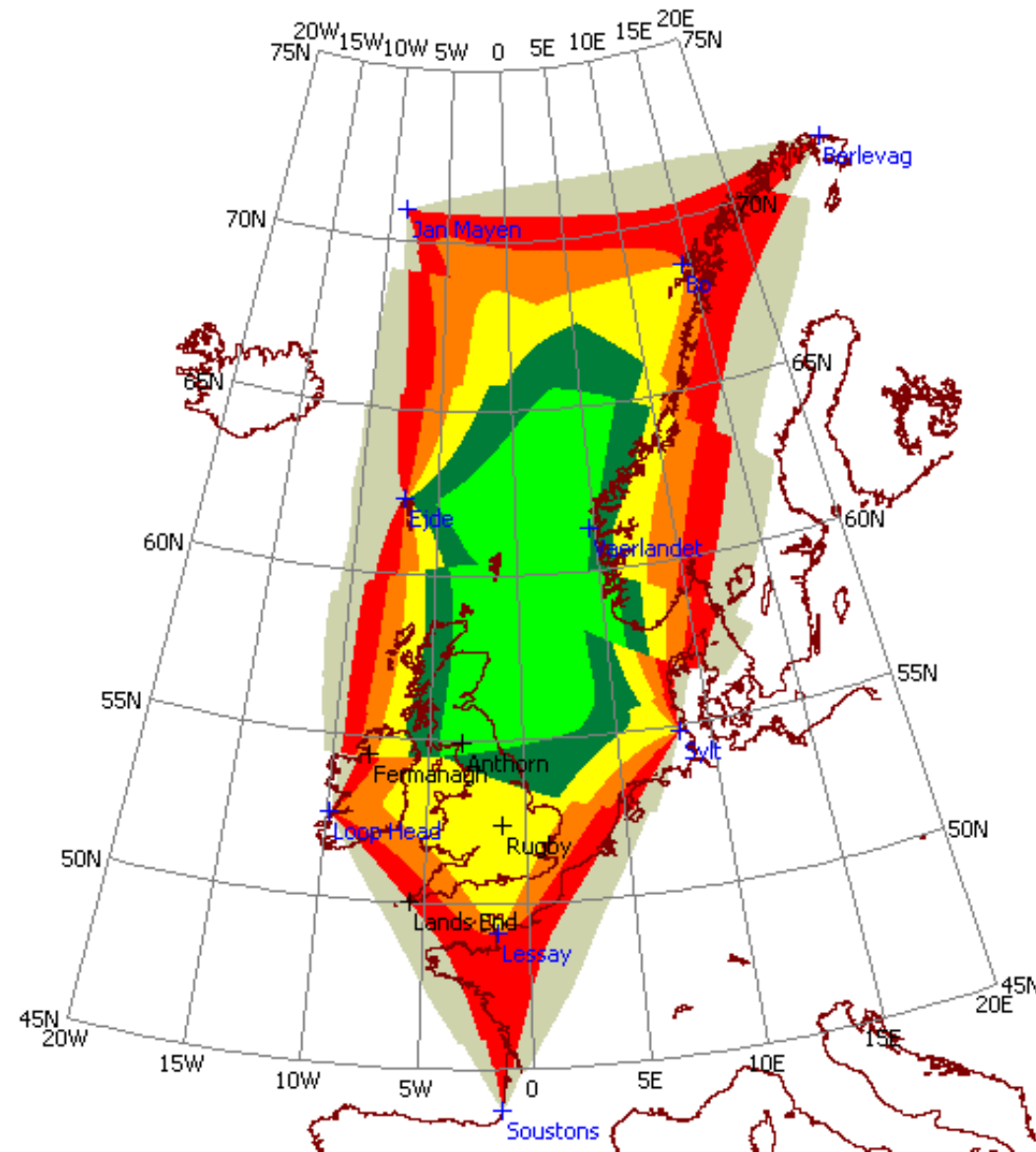
NW Europe Loran – A + F + LE : Neff

Eff NoM \geq 2 3 4 5 6 7

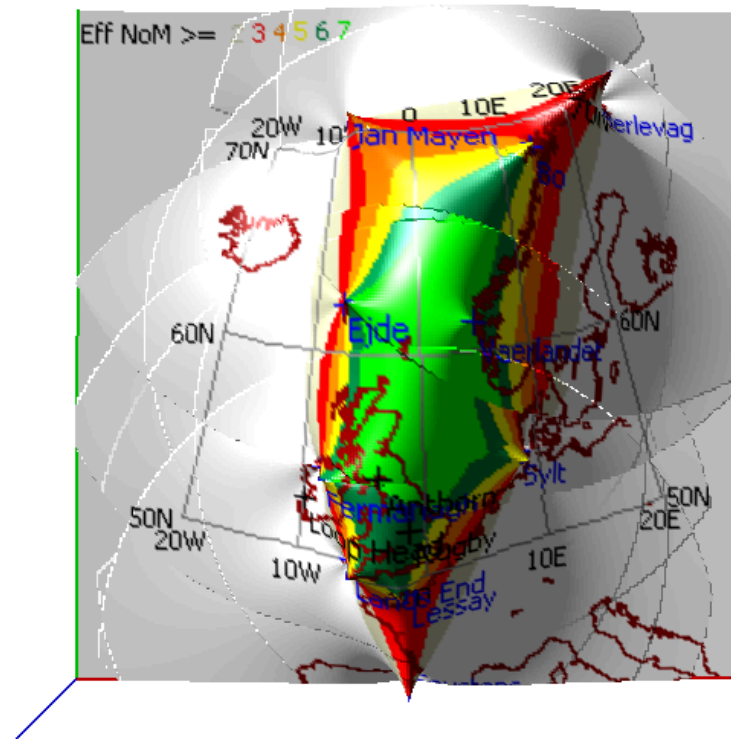


NW Europe Loran – A + LH : Neff

Eff NoM \geq 2 3 4 5 6 7



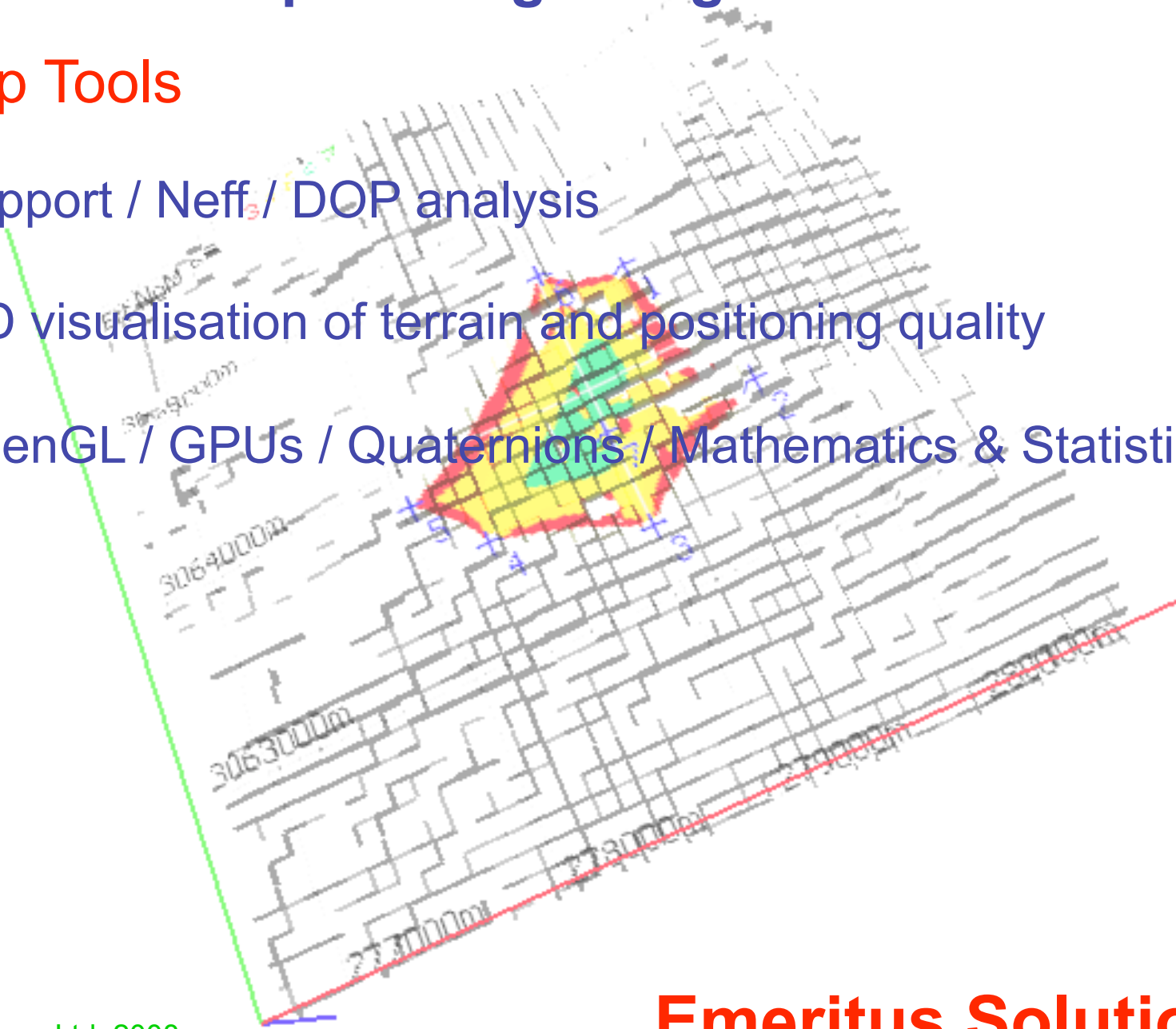
NW Europe Loran – A + F + LE : Neff



Sharp Tools for Optimising Navigation Sensor Arrays

■ Sharp Tools

- Support / Neff₃ / DOP analysis
- 3-D visualisation of terrain and positioning quality
- OpenGL / GPUs / Quaternions / Mathematics & Statistics



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- Digital Signal Processing : Algorithms and Mechanisation
- Computer Systems and Software Tools
 - SCSI Target disk and client interface [SCSIIt]
 - Application log file monitoring and exploitation [Leech]
 - Ethernet monitoring, logging and exploitation
- System Development and Verification



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