

Dr Paul Groves is a member of the Navigation and Positioning team of QinetiQ, specialising in integration and modelling of navigation systems. He has over 10 years experience in navigation systems research and development for air, land and marine applications, including with GNSS, inertial navigation, terrain-referenced navigation and various dead-reckoning sensors. He is an author of about 30 technical publications, including the new book, *Principles of GNSS, Inertial and Multi-Sensor Integrated Navigation Systems* (Artech House). He holds a BA/MA and a DPhil in physics from the University of Oxford. He is a fellow of the Royal Institute of Navigation, serving on the R&D and Technical committees, and an active member of the ION.

pdgroves@QinetiQ.com