

Biography of Ms. Natalie M. Frietsch

Author of the paper “VISION BASED LANDING SYSTEM FOR A VTOL-MAV”

Natalie Frietsch completed her degree in electrical engineering and information theory at the University of Karlsruhe, Germany in 2006. Afterwards she has joined the Institute of Systems Optimization in Karlsruhe and works as a Ph. D. candidate. Her research interests are navigation and control of unmanned aerial vehicles (UAV), as well as image processing and computer vision applications to UAVs.

