



4 DOWN, 50 TO GO; AN UPDATE ON HARBOR SURVEYS IN THE UNITED STATES

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ILA 36 – Orlando Florida

16-17 October 2007



What Requirements Must be Met?

◆ Requirements

- ◆ Accuracy, availability, integrity, continuity

◆ Accuracy Requirements

- ◆ Aviation: NPA – RNP 0.3 (309 meters)
- ◆ Maritime: HEA (8-20 meters)

◆ Limitations

- ◆ Spatial and temporal variations in TOA observed by the receiver and presented to the position solution algorithm

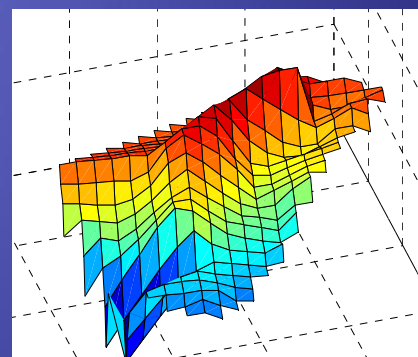
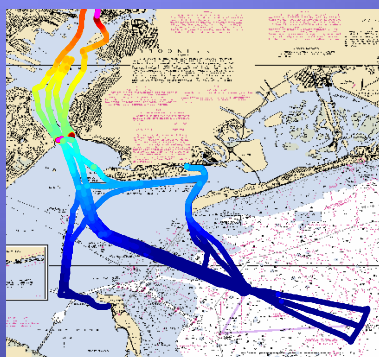


Maritime Solution: HEA Nav Concept

◆ ASF corrected TOAs

◆ To remove spatial component:

- ◆ Use published grid, interpolate between grid points
- ◆ Issues include grid density, regions of interest, and grid creation



◆ To remove temporal component:

◆ Local monitor receiver, broadcast offsets over LDC

- ◆ Issues include correlation distance, monitor averaging, multiple monitor interpolation



Goals for Today

◆ Spatial ASF Grids

- ◆ Harbor Survey Methodology
- ◆ Converting to a grid
- ◆ Required grid density
- ◆ Performance examples

◆ Temporal Corrections

- ◆ LDC architecture for live broadcast of differential corrections

◆ Prototype eLoran Receiver

- ◆ Sample navigation performance



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Harbor Survey Methodology

◆ Identify the HEA area and generate sail plans that will cover all of the areas of interest

- ◆ typically a 200m spacing
- ◆ Tracks must be planned on inside and outside edges of channels
- ◆ in general the area of interest needs to be over-bounded.

◆ Conduct field test

- ◆ Static monitor somewhere in the harbor area (harbor monitor)
- ◆ Perform data collection mapping throughout the harbor; measure ASFs and GPS position



Harbor Survey Methodology

- ◆ **Convert the measured ASFs to relative ASFs by subtracting the reference site ASF for the corresponding times of the vessel ASF measurements.**
 - ◆ This eliminates any temporal variations (due to daily, seasonal, weather, or system timing effects) from the measurements.
- ◆ **Create spatial ASF grid from tracks of relative ASFs**
- ◆ **Procedure developed and refined over a series of harbor surveys**
 - ◆ New London
 - ◆ New York
 - ◆ Norfolk
 - ◆ Boston



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NY Harbor Phase I

Continuous vessel tracks in upper harbor

Static locations in upper harbor

Vessel

Van on shore



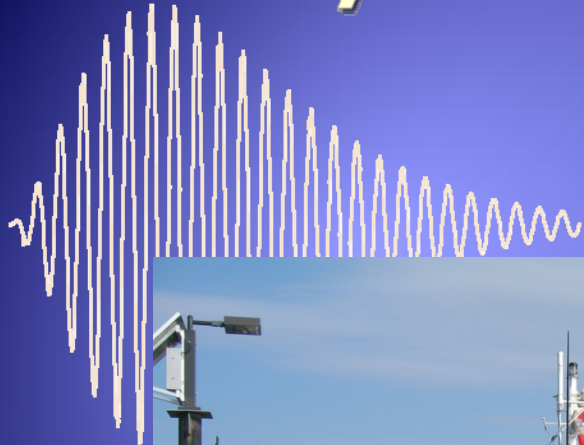
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Survey Vessel, Launch#5

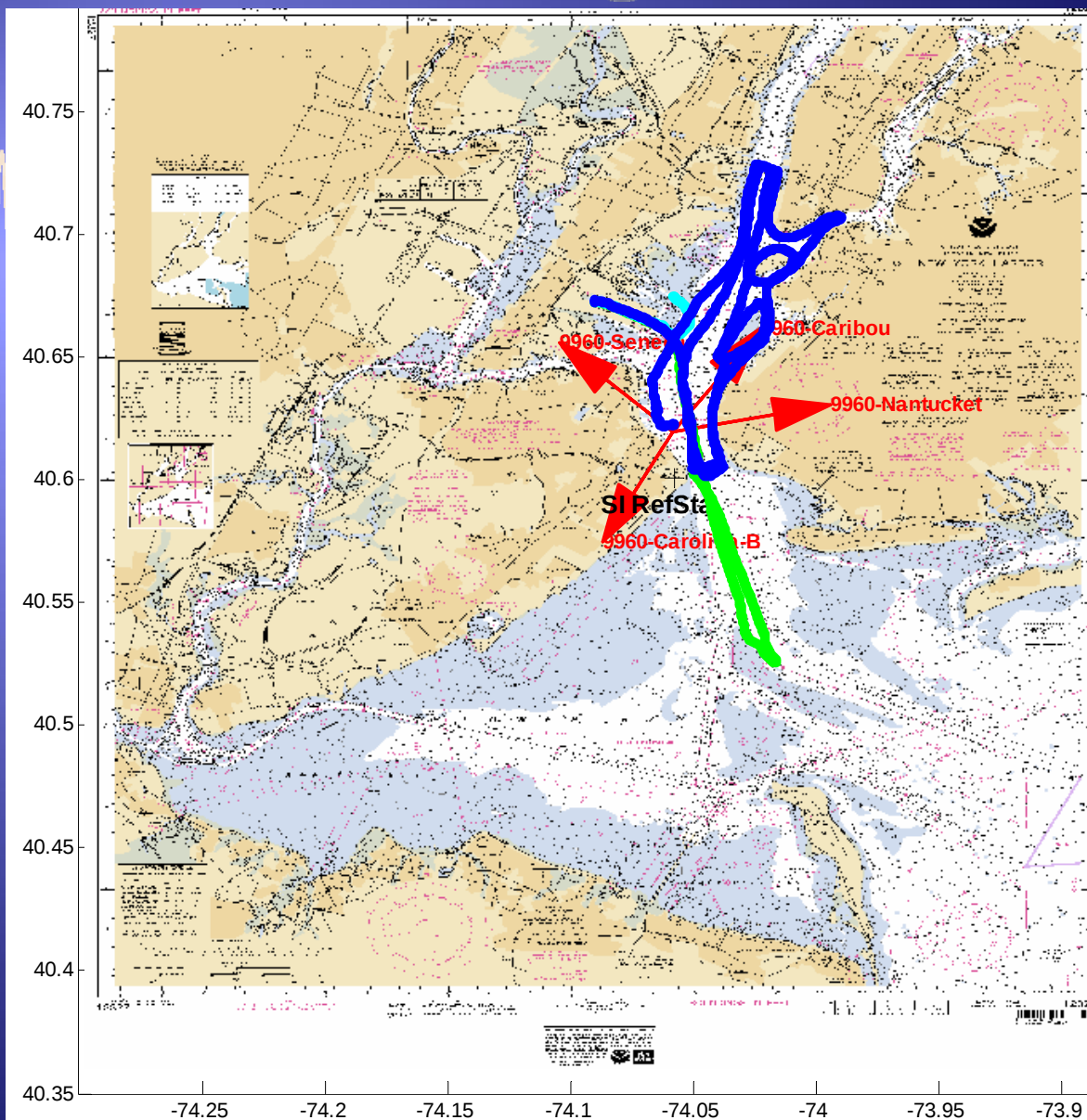
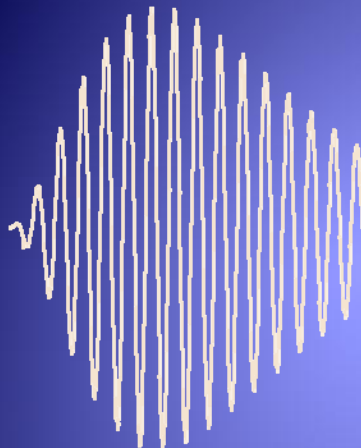


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NY Harbor PH1 Coverage



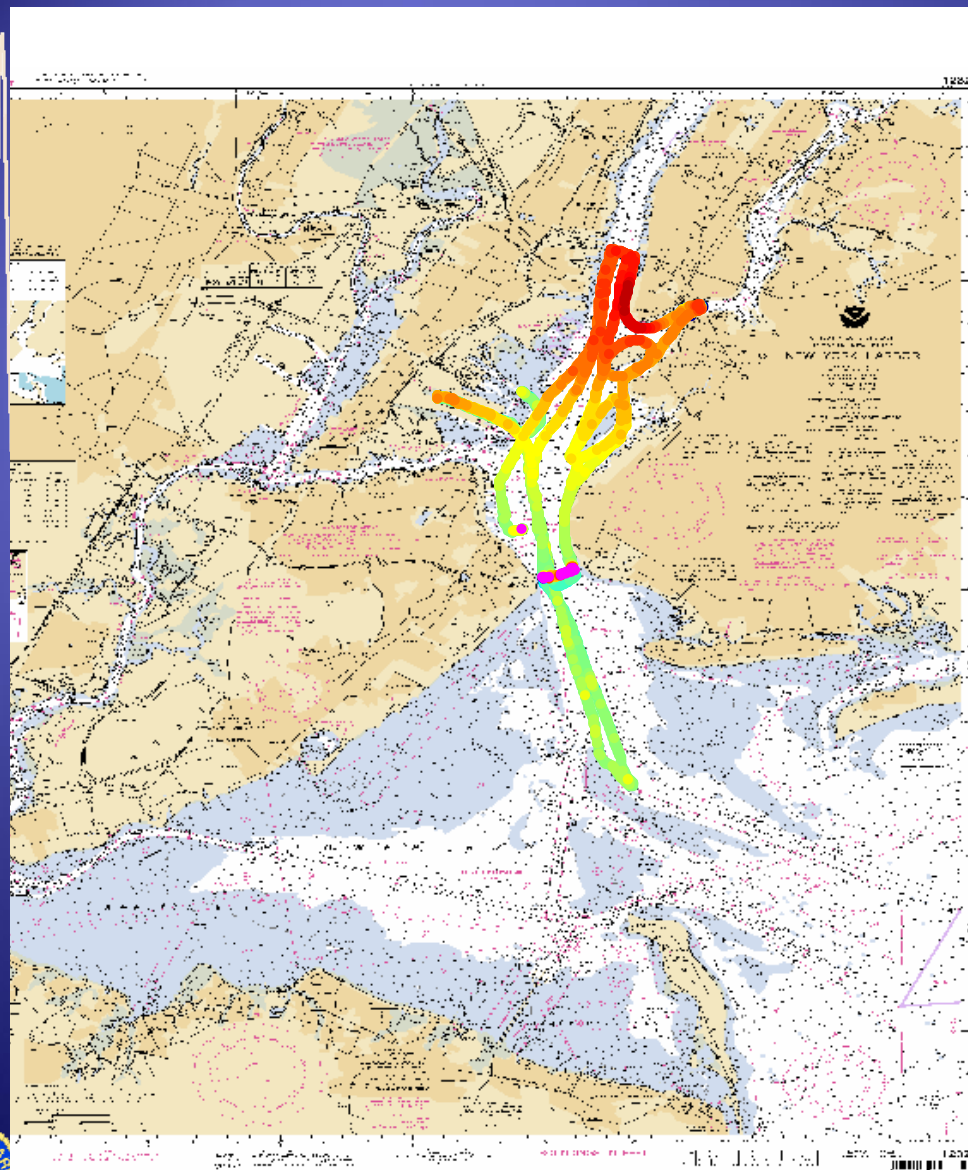
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Nantucket Relative ASFs



- ASF<=-1
- -1<ASF<=-0.95
- -0.95<ASF<=-0.9
- -0.9<ASF<=-0.85
- -0.85<ASF<=-0.8
- -0.8<ASF<=-0.75
- -0.75<ASF<=-0.7
- -0.7<ASF<=-0.65
- -0.65<ASF<=-0.6
- -0.6<ASF<=-0.55
- -0.55<ASF<=-0.5
- -0.5<ASF<=-0.45
- -0.45<ASF<=-0.4
- -0.4<ASF<=-0.35
- -0.35<ASF<=-0.3
- -0.3<ASF<=-0.25
- -0.25<ASF<=-0.2
- -0.2<ASF<=-0.15
- -0.15<ASF<=-0.1
- -0.1<ASF<=-0.05
- -0.05<ASF<=-1.1102e-016
- -1.1102e-016<ASF<=0.05
- 0.05<ASF<=0.1
- 0.1<ASF<=0.15
- 0.15<ASF<=0.2
- 0.2<ASF<=0.25
- 0.25<ASF<=0.3
- 0.3<ASF<=0.35
- 0.35<ASF<=0.4
- 0.4<ASF<=0.45
- 0.45<ASF<=0.5
- 0.5<ASF<=0.55
- 0.55<ASF<=0.6
- 0.6<ASF<=0.65
- 0.7>ASF



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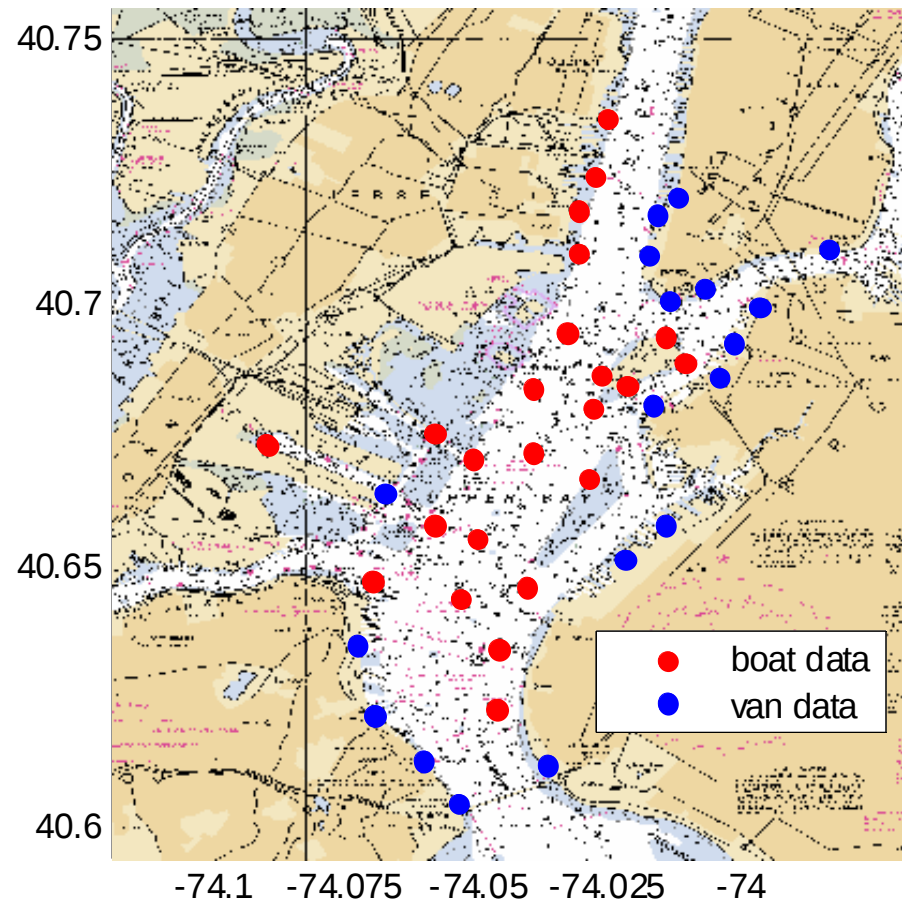
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Static Points

◆ Vessel collected data at 25 static locations in the harbor

- ◆ Held station next to buoy, pier, etc.

◆ Van collected data at 19 static locations around the harbor



NY Harbor Phase II

Different Vessel

Continuous Track in lower harbor

Repeat Upper harbor

12 static locations



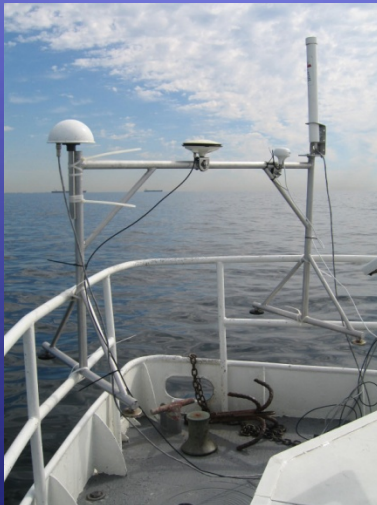
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Survey Vessel, Jeanne II



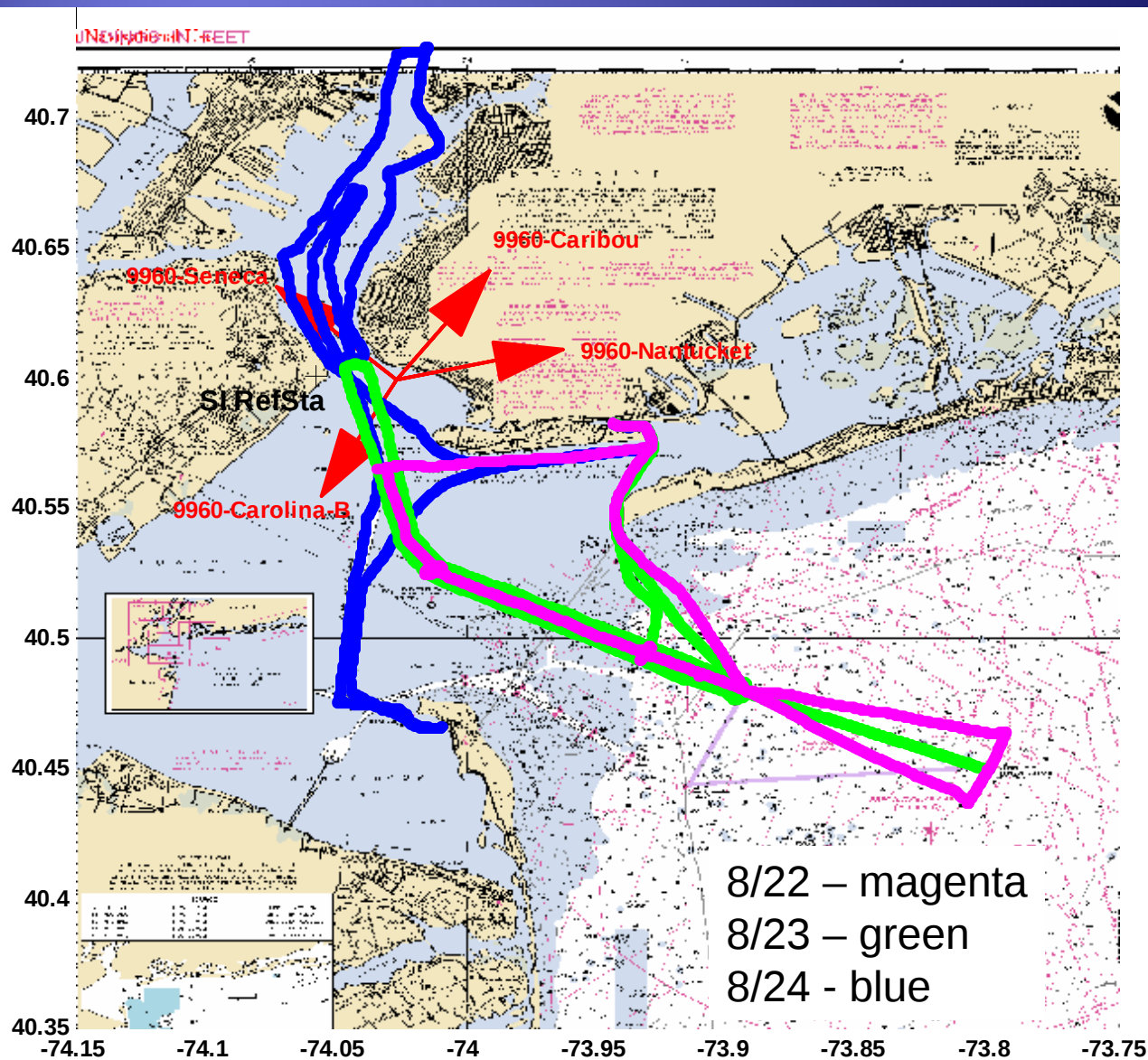
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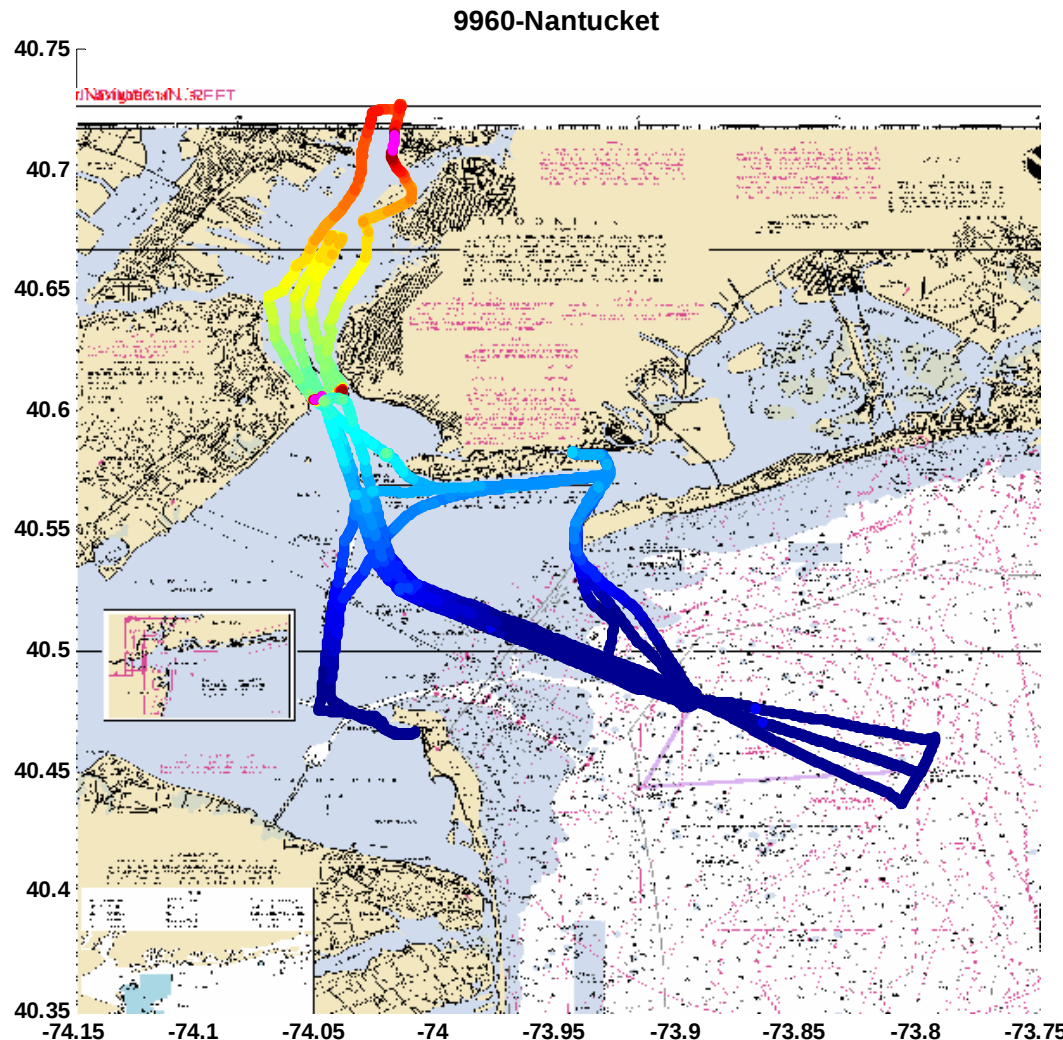
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NY Harbor Phase II Coverage



Nantucket Relative ASFs



- ASF<=-1
- -1<ASF<=-0.95
- -0.95<ASF<=-0.9
- -0.9<ASF<=-0.85
- -0.85<ASF<=-0.8
- -0.8<ASF<=-0.75
- -0.75<ASF<=-0.7
- -0.7<ASF<=-0.65
- -0.65<ASF<=-0.6
- -0.6<ASF<=-0.55
- -0.55<ASF<=-0.5
- -0.5<ASF<=-0.45
- -0.45<ASF<=-0.4
- -0.4<ASF<=-0.35
- -0.35<ASF<=-0.3
- -0.3<ASF<=-0.25
- -0.25<ASF<=-0.2
- -0.2<ASF<=-0.15
- -0.15<ASF<=-0.1
- -0.1<ASF<=-0.05
- -0.05<ASF<=-1.1102e-016
- -1.1102e-016<ASF<=0.05
- 0.05<ASF<=0.1
- 0.1<ASF<=0.15
- 0.15<ASF<=0.2
- 0.2<ASF<=0.25
- 0.25<ASF<=0.3
- 0.3<ASF<=0.35
- 0.35<ASF<=0.4
- 0.4<ASF<=0.45
- 0.45<ASF<=0.5
- 0.5<ASF<=0.55
- 0.55<ASF<=0.6
- 0.6<ASF<=0.65
- 0.7>ASF



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Thames River

USCG AUX Vessel Myst

Oct 2006

Nov 2006

Test Van

Mar 2006

Other vessels

Mar, Apr 2006

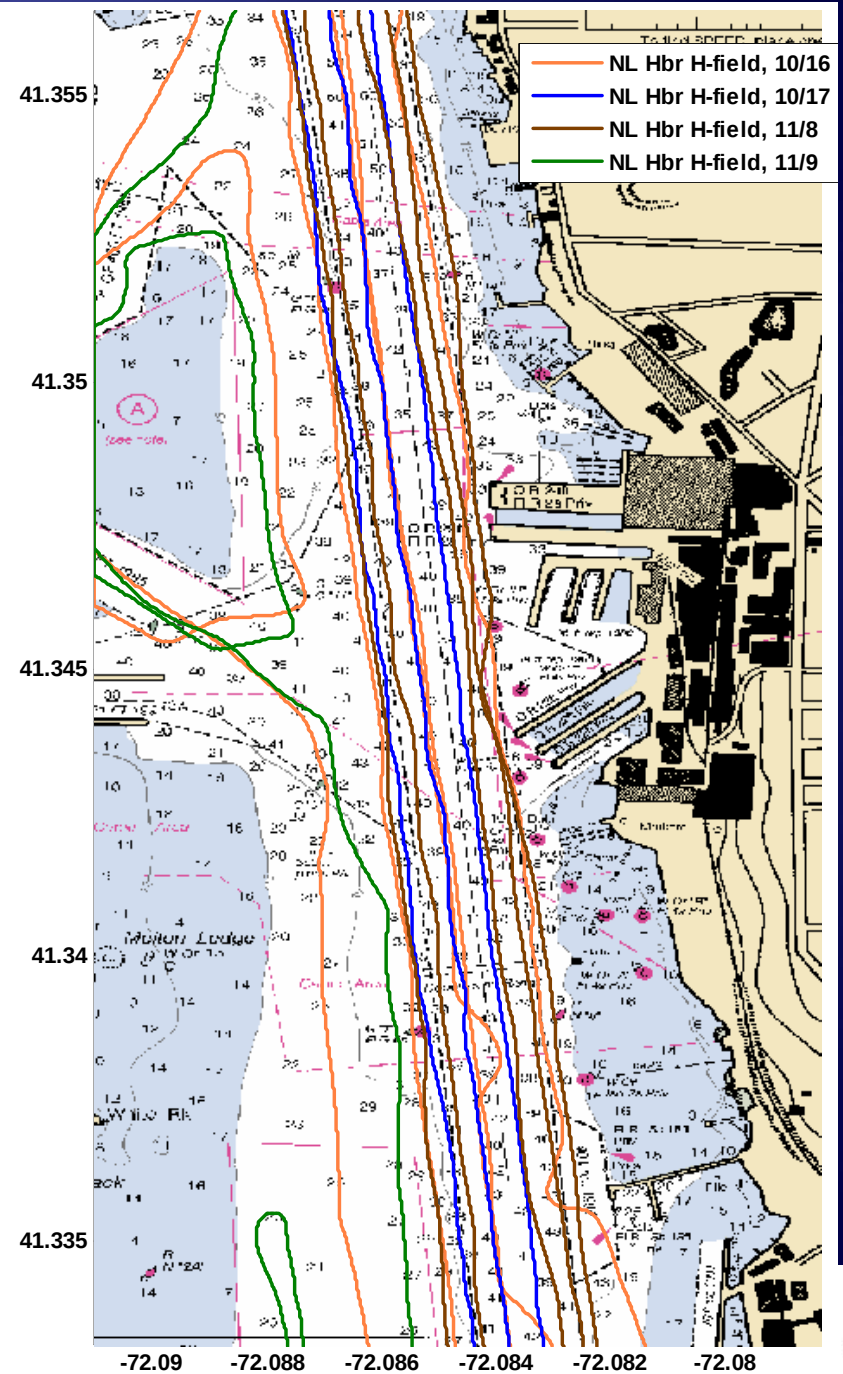
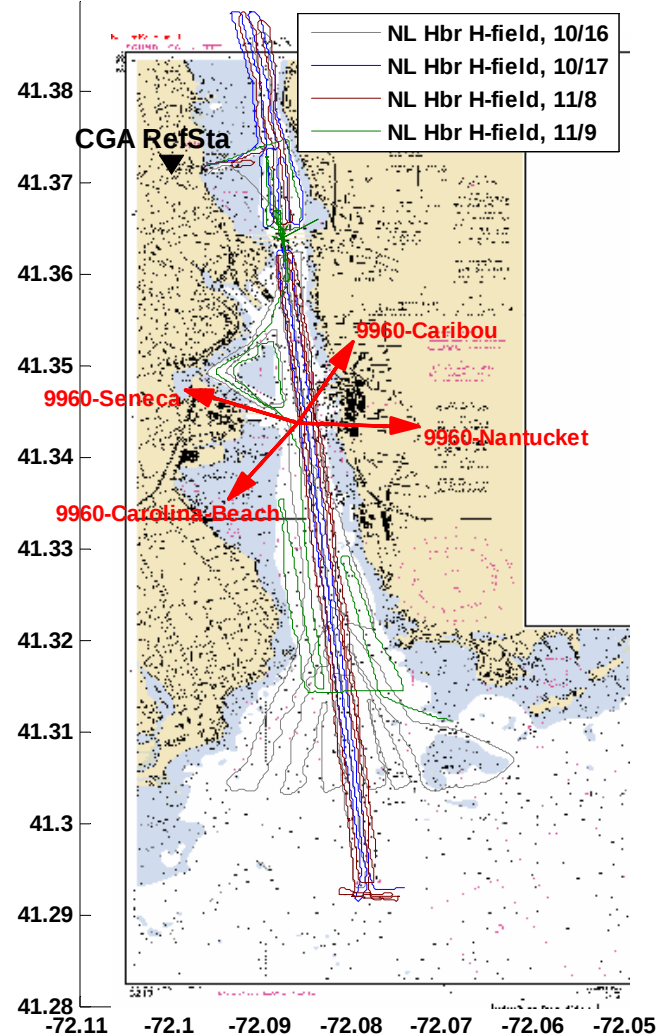


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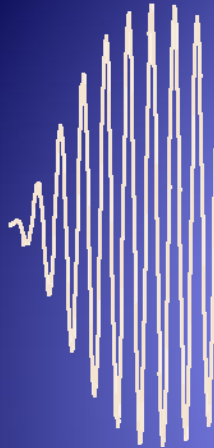
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Locations/Tracks

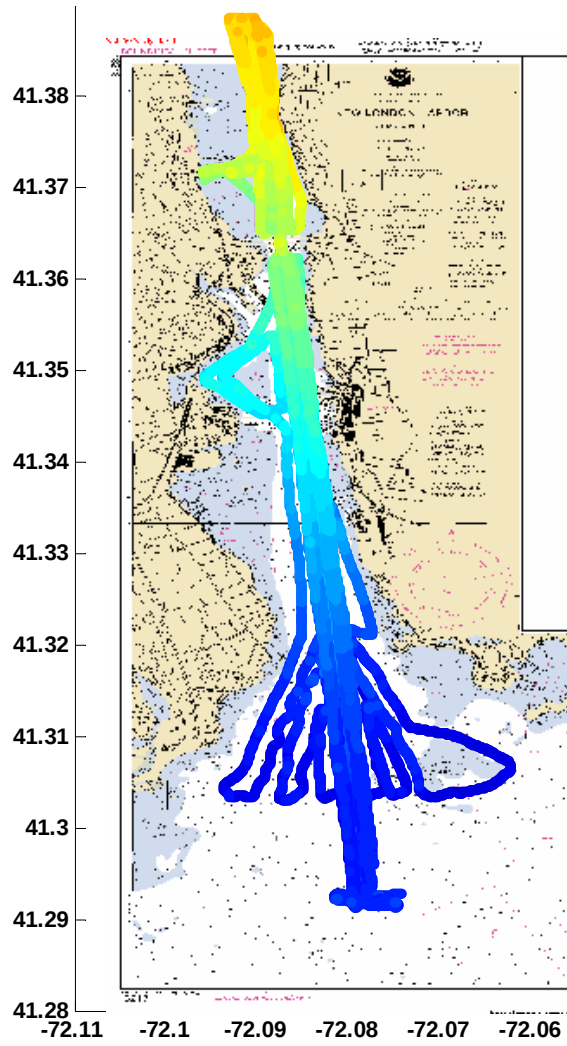


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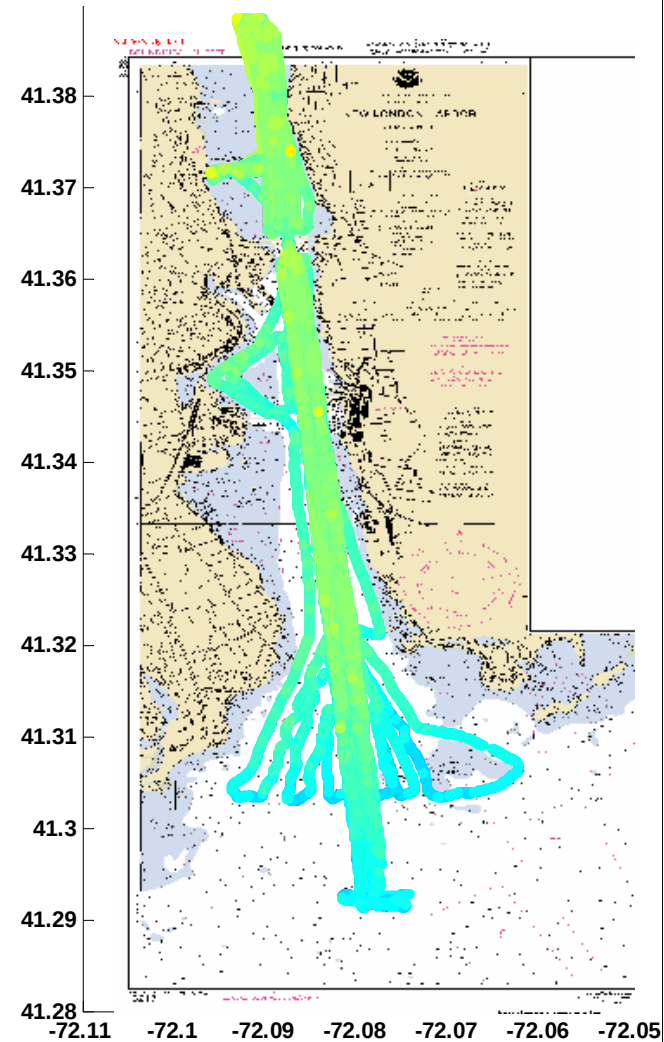
Thames Relative ASF Data



9960-Nantucket



9960-Seneca



- -0.95<ASF<=-0.9
- -0.9<ASF<=-0.85
- -0.85<ASF<=-0.8
- -0.8<ASF<=-0.75
- -0.75<ASF<=-0.7
- -0.7<ASF<=-0.65
- -0.65<ASF<=-0.6
- -0.6<ASF<=-0.55
- -0.55<ASF<=-0.5
- -0.5<ASF<=-0.45
- -0.45<ASF<=-0.4
- -0.4<ASF<=-0.35
- -0.35<ASF<=-0.3
- -0.3<ASF<=-0.25
- -0.25<ASF<=-0.2
- -0.2<ASF<=-0.15
- -0.15<ASF<=-0.1
- -0.1<ASF<=-0.05
- -0.05<ASF<=0
- 0<ASF<=0.05
- 0.05<ASF<=0.1
- 0.1<ASF<=0.15
- 0.15<ASF<=0.2
- 0.2<ASF<=0.25
- 0.25<ASF<=0.3
- 0.3<ASF<=0.35
- 0.35<ASF<=0.4
- 0.4<ASF<=0.45
- 0.45<ASF<=0.5
- 0.5<ASF<=0.55
- 0.55<ASF<=0.6
- 0.6<ASF<=0.65
- 0.65<ASF<=0.7
- 0.7<ASF<=0.75
- 0.75<ASF<=0.8
- 0.8<ASF<=0.85
- 0.85<ASF<=0.9
- 0.9<ASF<=0.95
- 1>ASF



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Norfolk

Chesapeake Bay approach channel into Norfolk Harbor



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Survey Vessel, Halcyon Lace

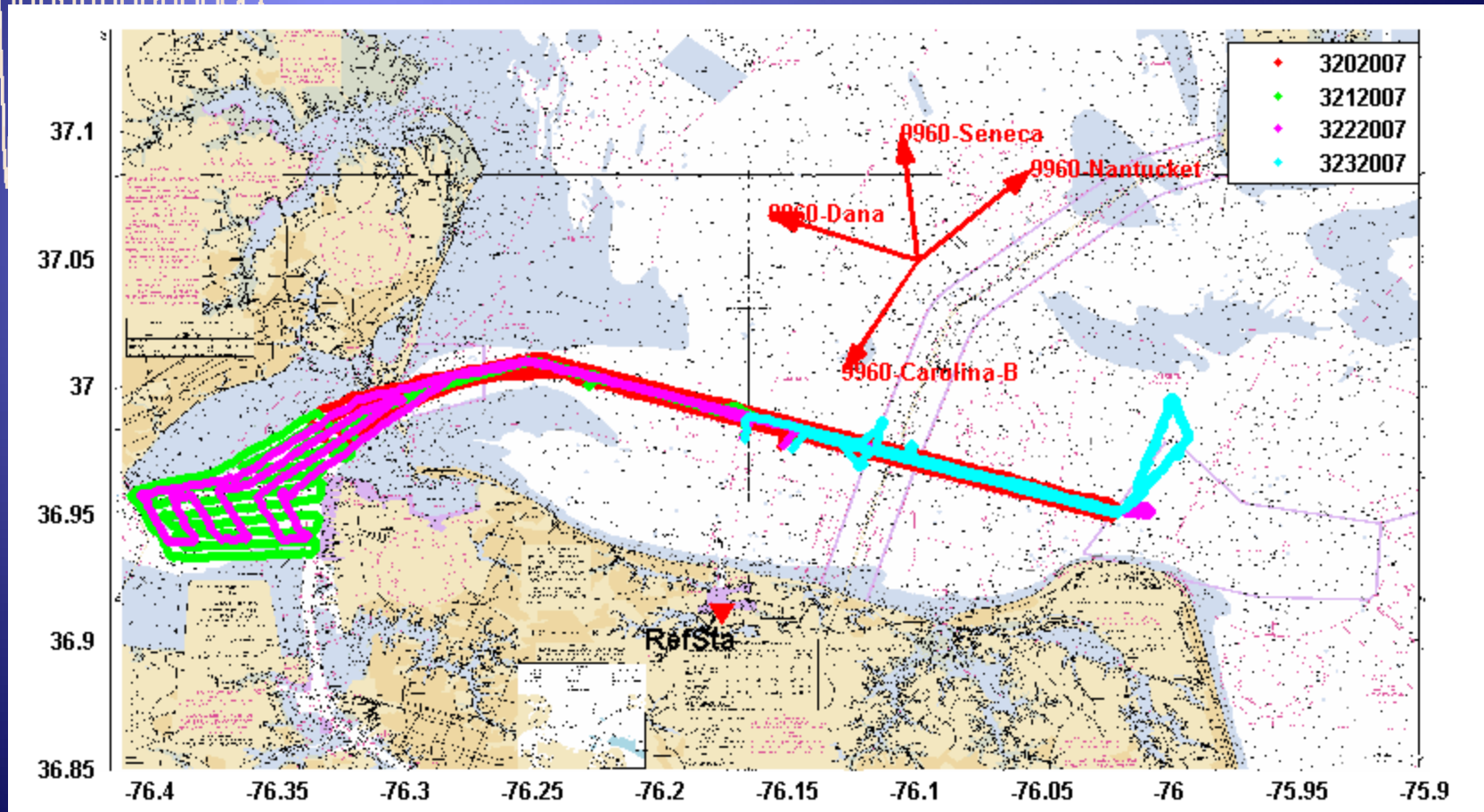


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Norfolk Harbor Coverage



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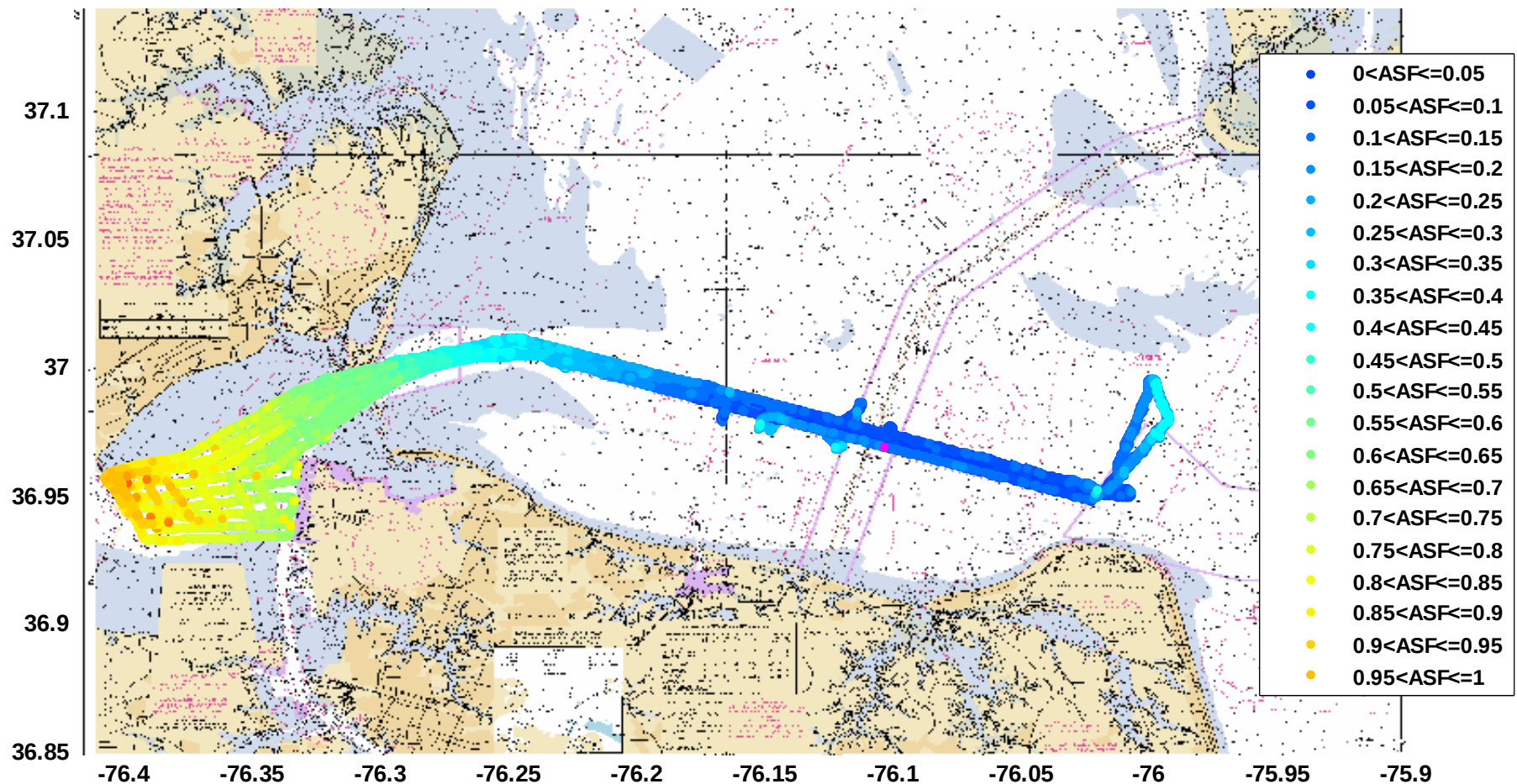
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Seneca Relative ASFs

9960-Seneca



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Boston Harbor

Continuous tracks inner harbor, main channels, and entrance approach area



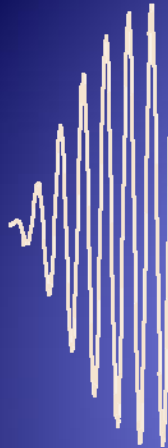
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Survey Vessel, Three J's

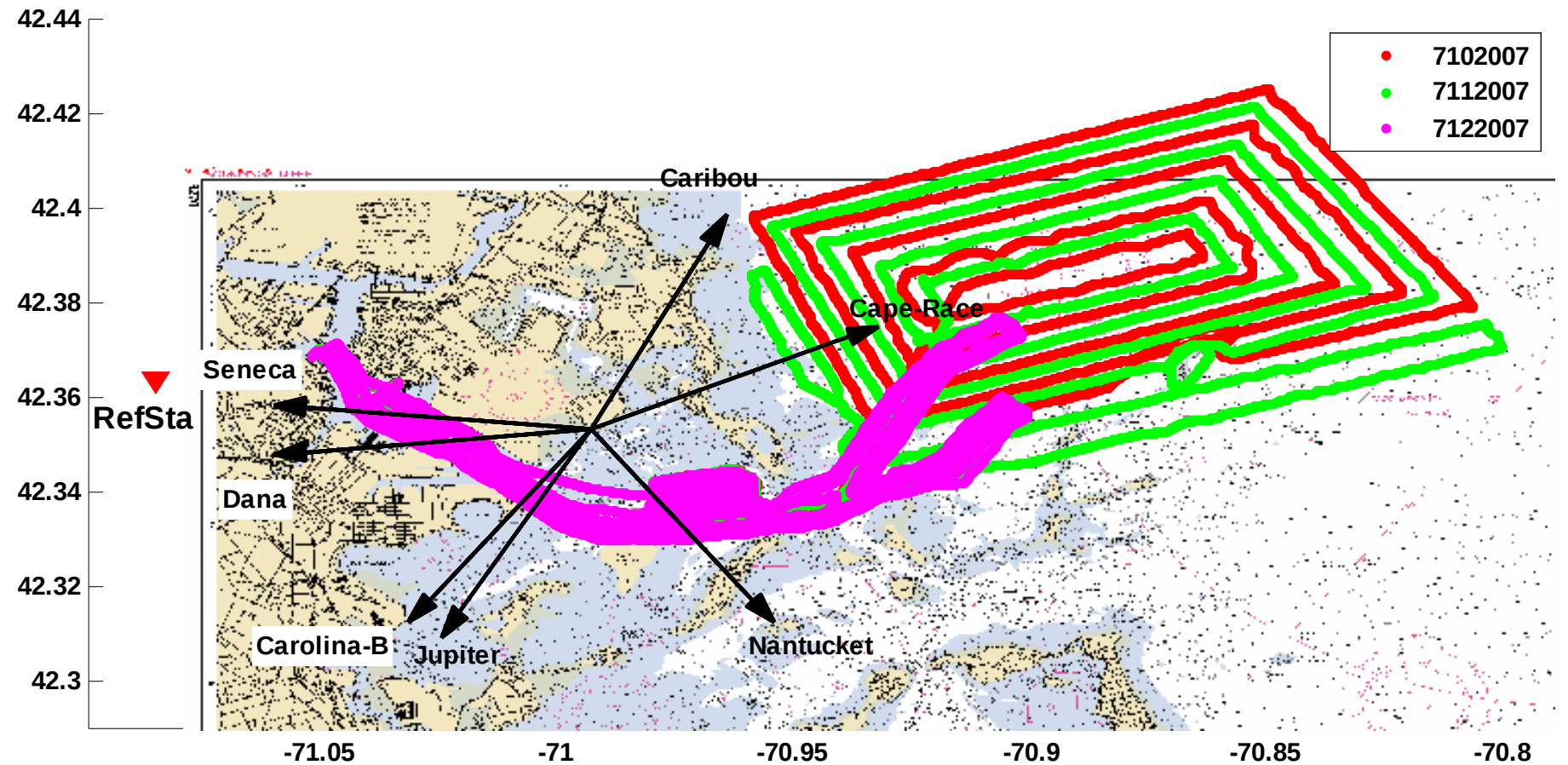


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Boston Coverage Area



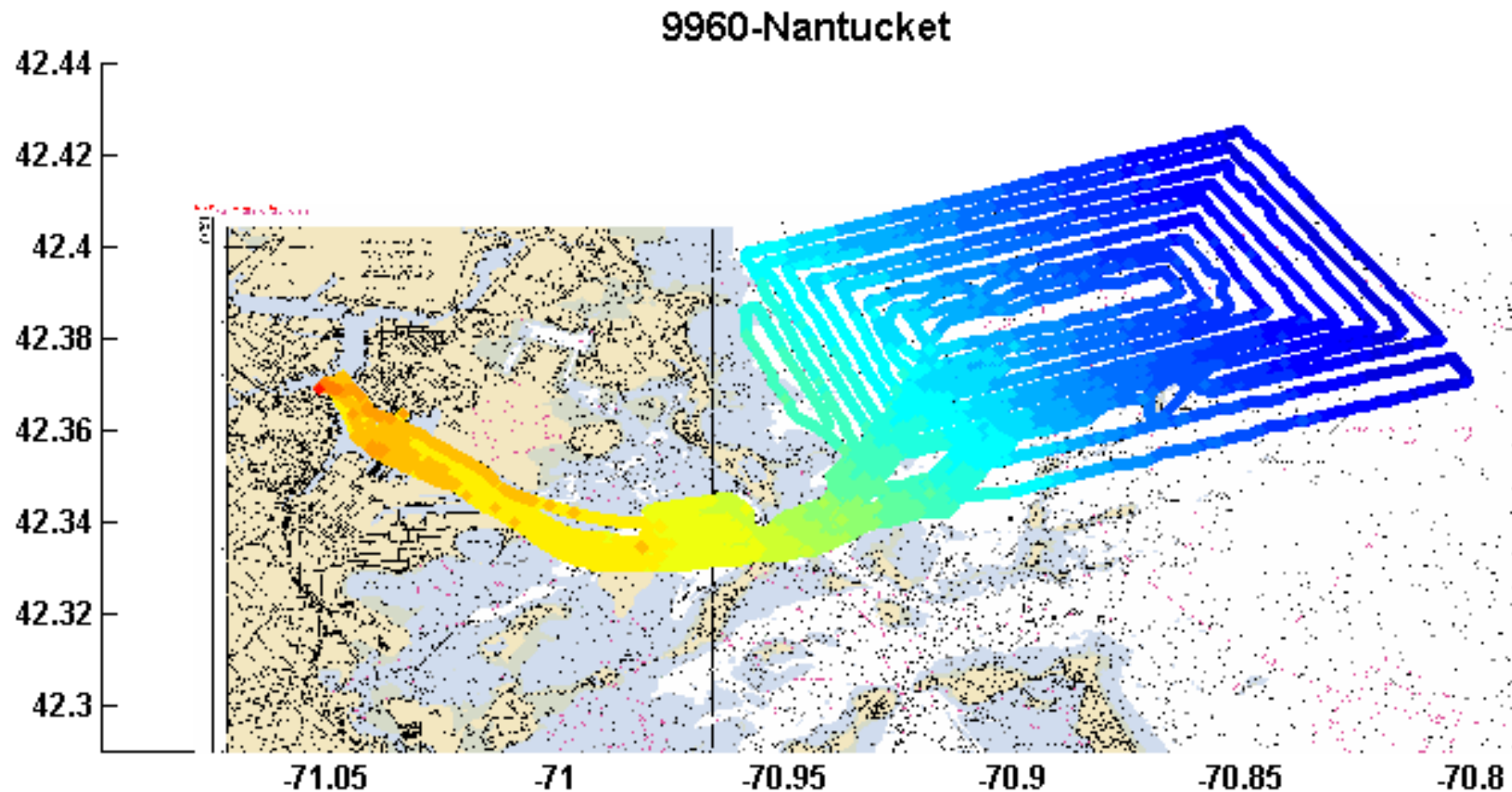
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Nantucket Relative ASFs



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Data Processing

- ◆ ASFs/TOAs processed to remove receiver filtering and velocity vector toward towers (and time lag)
- ◆ Precise track computed using L1/L2 GPS data post-processed with GrafNav s/w using CORS reference stations
- ◆ ASFs recalculated using precise track position and unfiltered TOAs
- ◆ Relative ASFs calculated
 $(ASF_{\text{boat}} - ASF_{\text{ref}})$



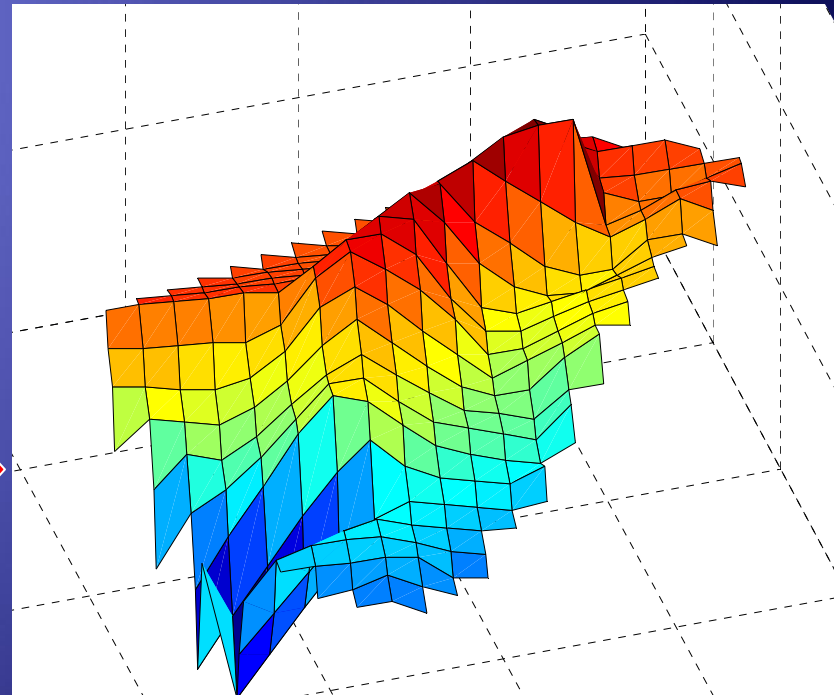
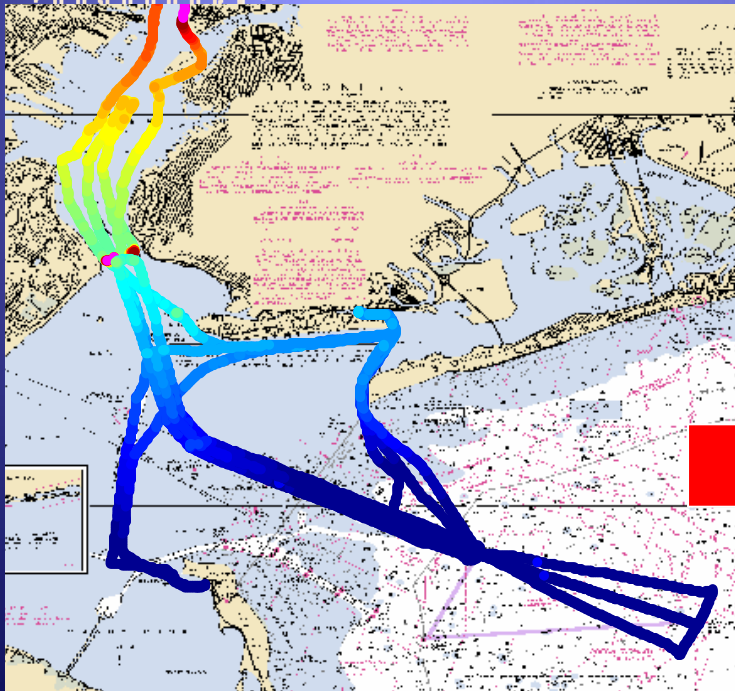
Spatial ASF Grids

- Method for converting tracks to a grid
- Required grid density
- Performance examples



Grid Development

- ◆ Overdetermined least squares estimation method akin to an “inverse interpolation” (ION GNSS 2006)



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Grid Creation

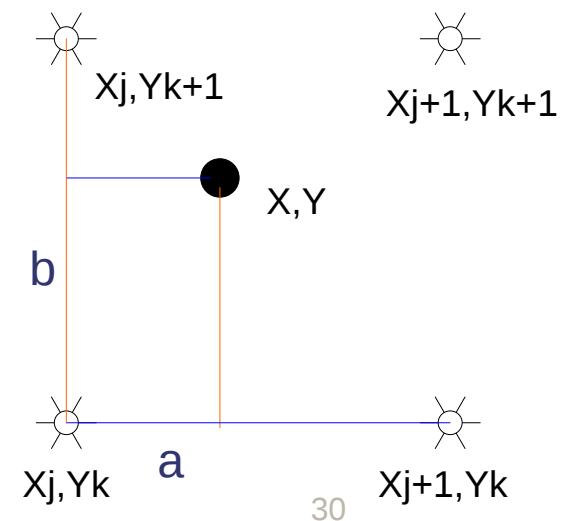
◆ Recall standard linear interpolation:

- ◆ Given a function at grid points, we can interpolate a general $F(x, y)$ by

$$F(x, y) = (1-a)(1-b)F(x_j, y_k) + a(1-b)F(x_{j+1}, y_k) + b(1-a)F(x_j, y_{k+1}) + abF(x_{j+1}, y_{k+1})$$

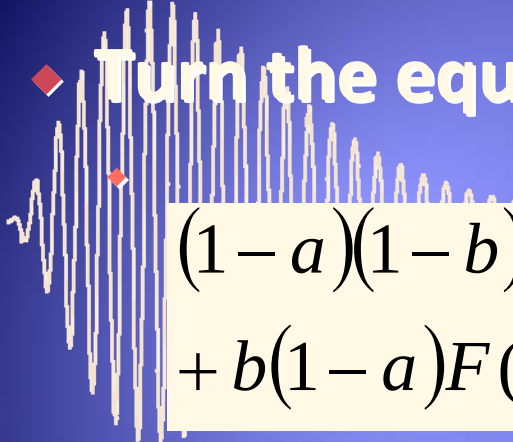
- ◆ with

$$a = \frac{x - x_j}{x_{j+1} - x_j} \quad \text{and} \quad b = \frac{y - y_k}{y_{k+1} - y_k}$$



“Inverse Interpolation”

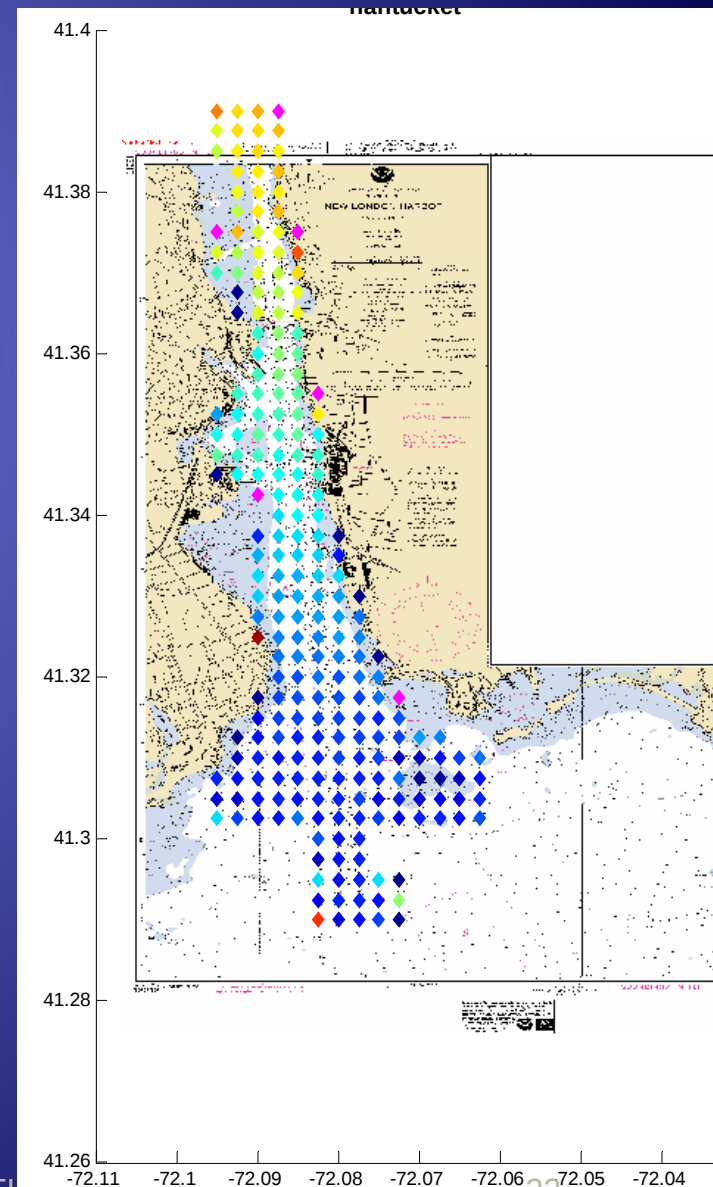
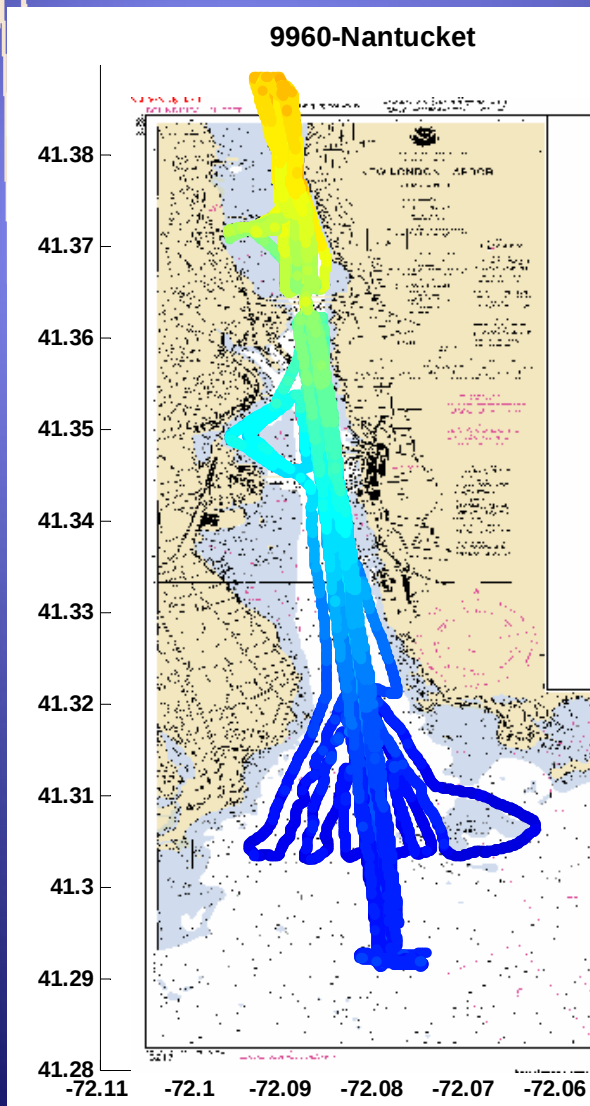
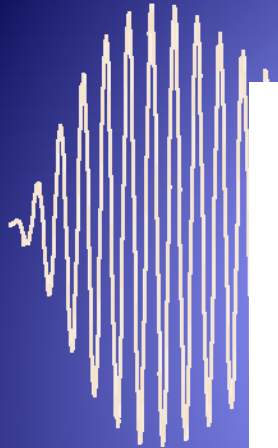
- ◆ Turn the equations around:


$$(1-a)(1-b)F(x_j, y_k) + a(1-b)F(x_{j+1}, y_k) + b(1-a)F(x_j, y_{k+1}) + abF(x_{j+1}, y_{k+1}) = F(x, y)$$

- ◆ a, b, and F(x, y) are known
- ◆ so each data point yields a linear equation in 4 unknowns
- ◆ solve large set of simultaneous linear equations to get grids



Sample Grid - Nantucket



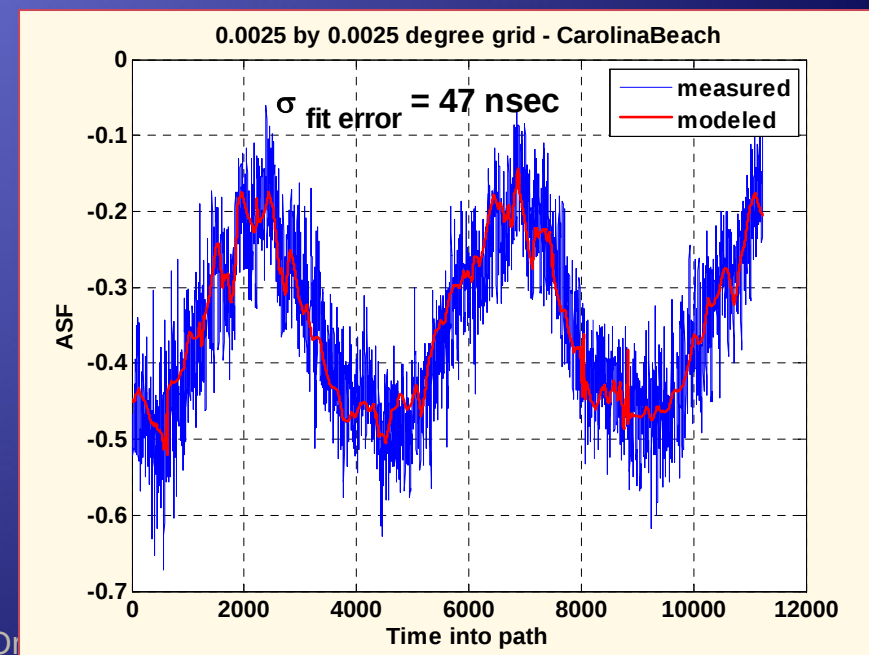
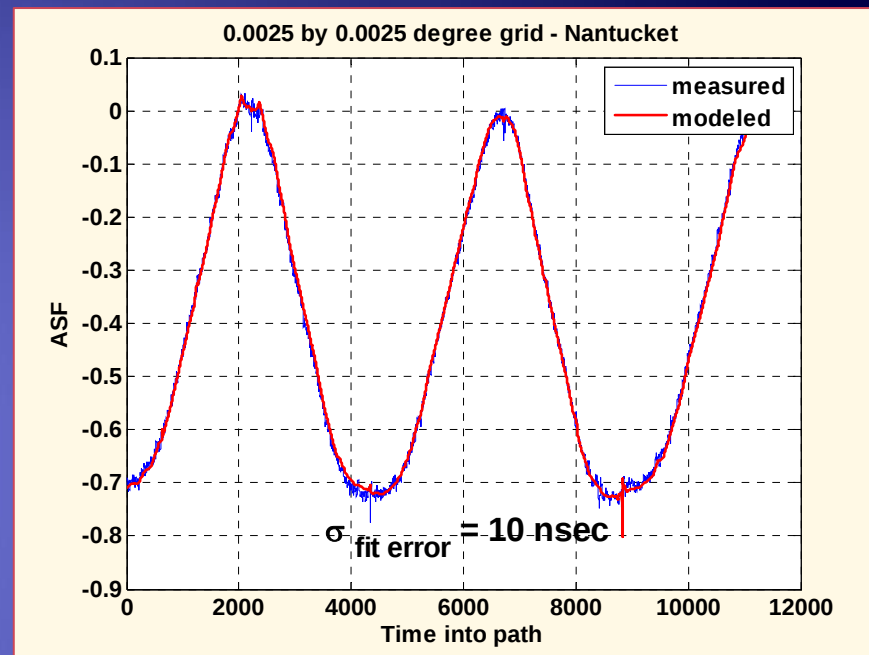
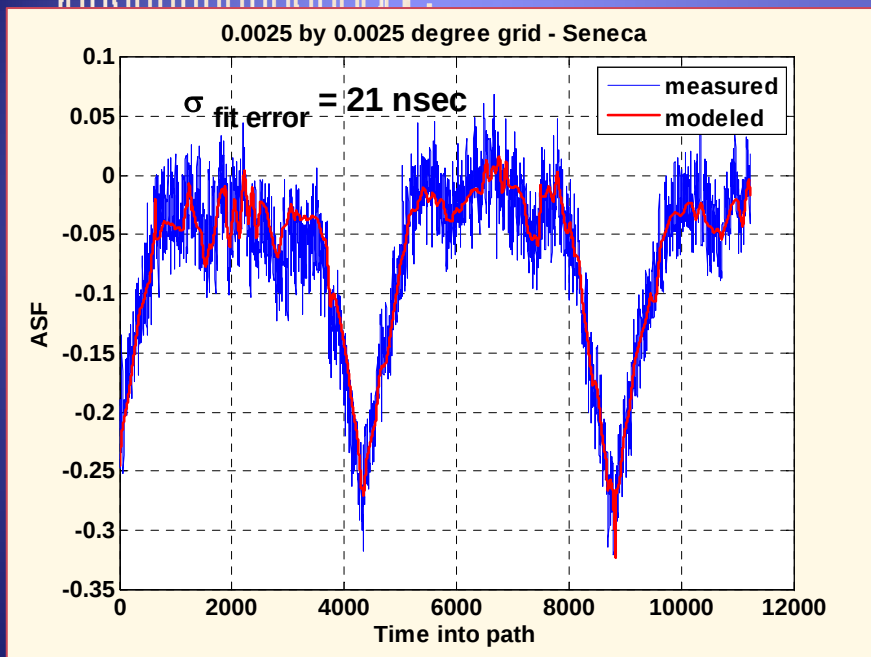
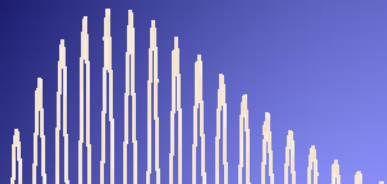
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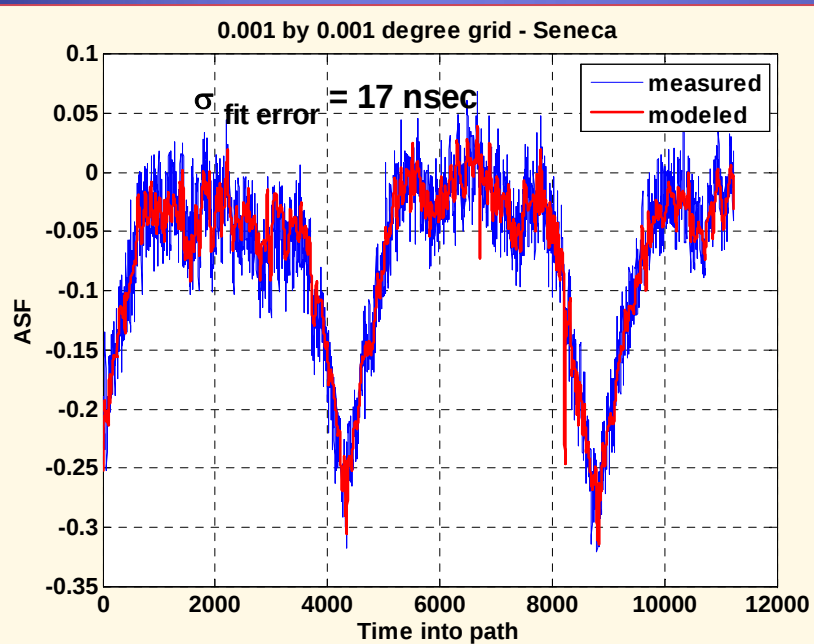
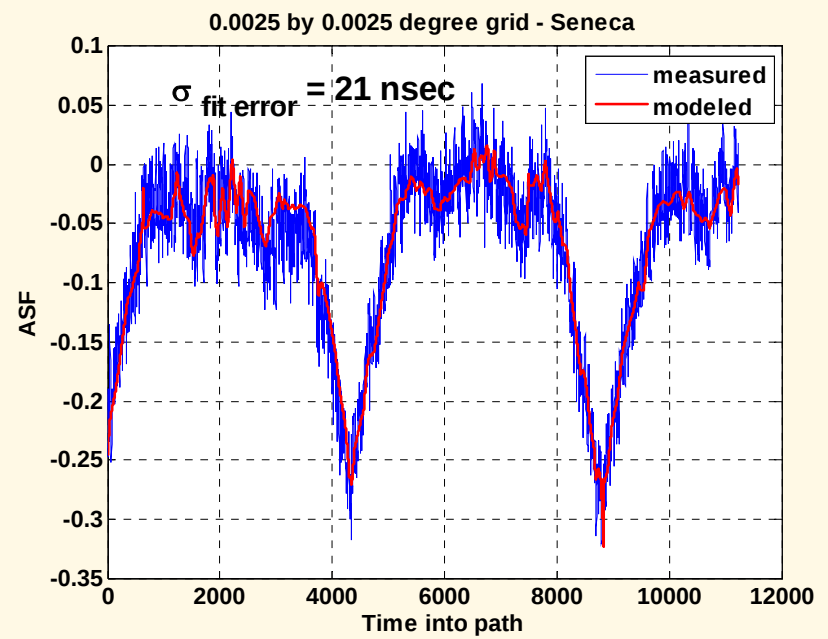
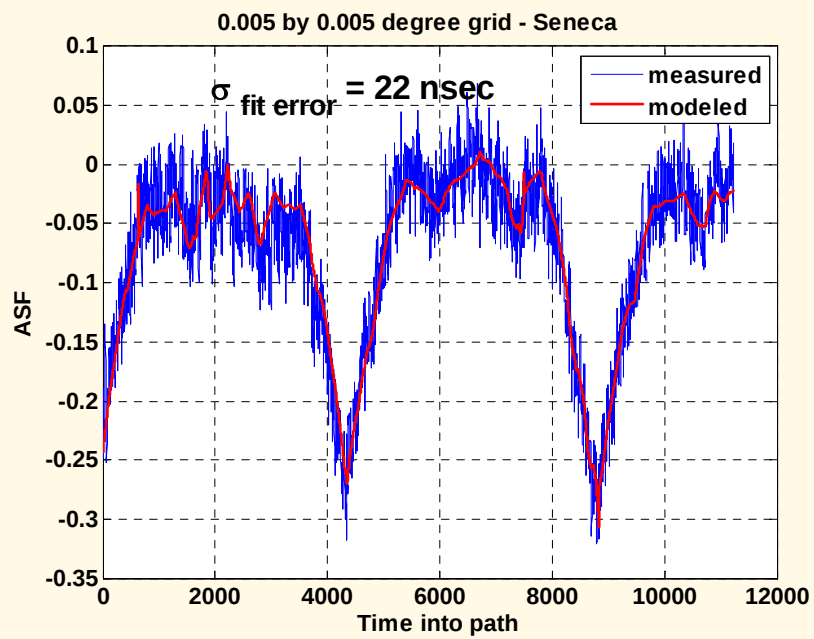
Grid fit to data



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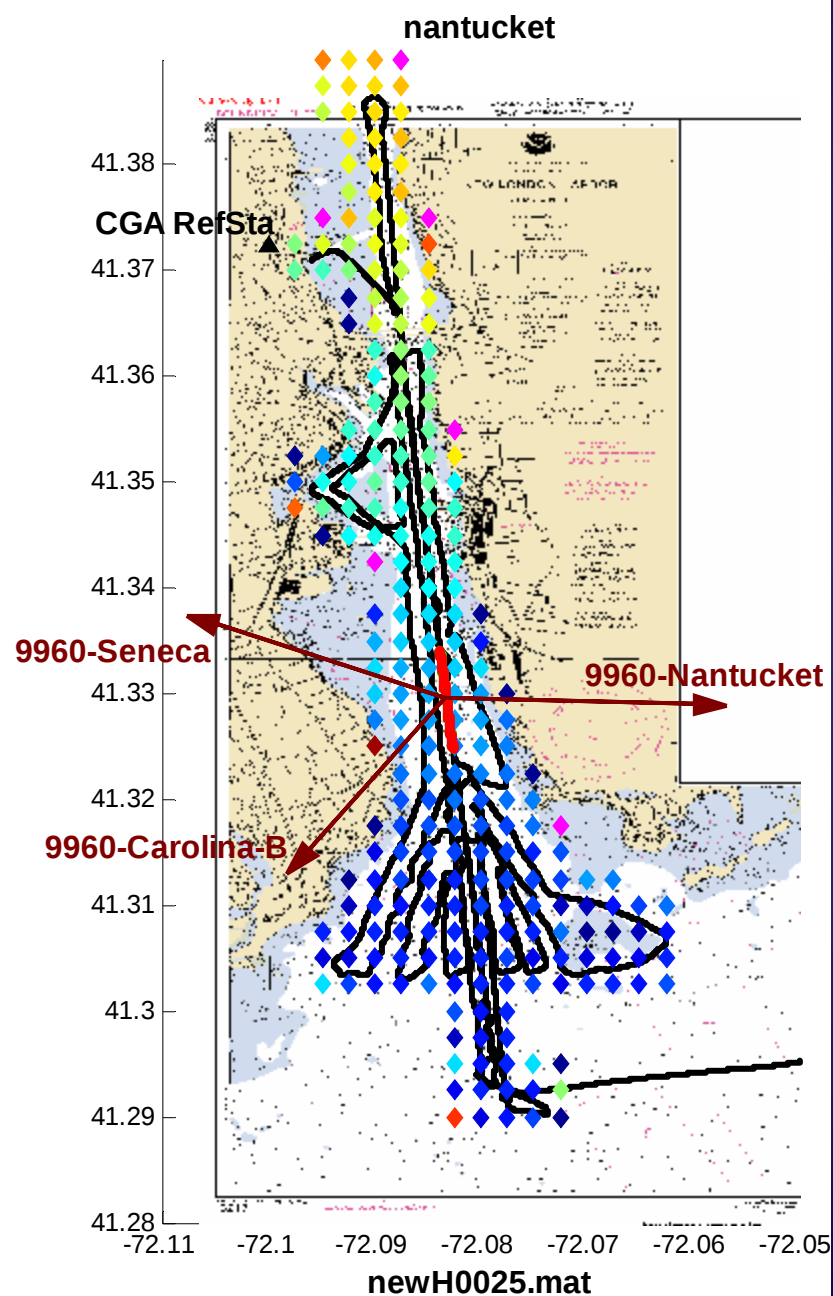
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Resolution	~meters	Fit error in nsec		
		Seneca	Nantucket	Carolina Beach
0.0005	55	13	3	30
0.0010	110	17	7	40
0.0015	165	20	9	44
0.0020	225	21	10	47
0.0025	280	21	10	47
0.0050	560	22	10	48

Thames Performance Example

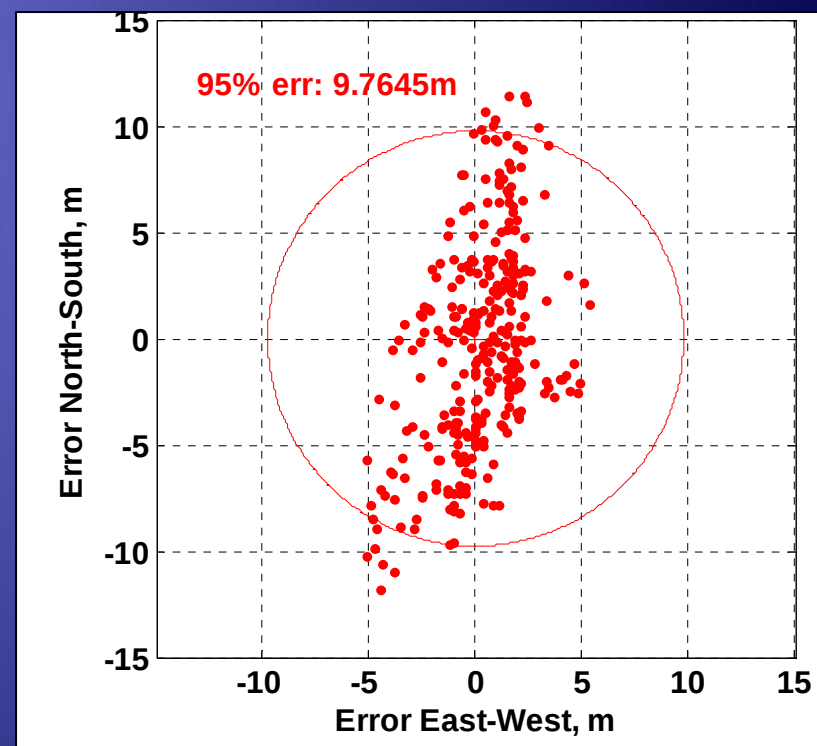
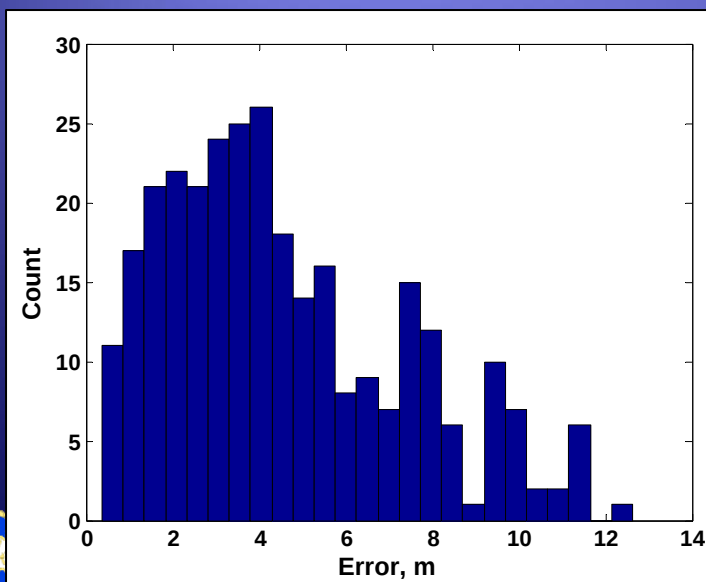
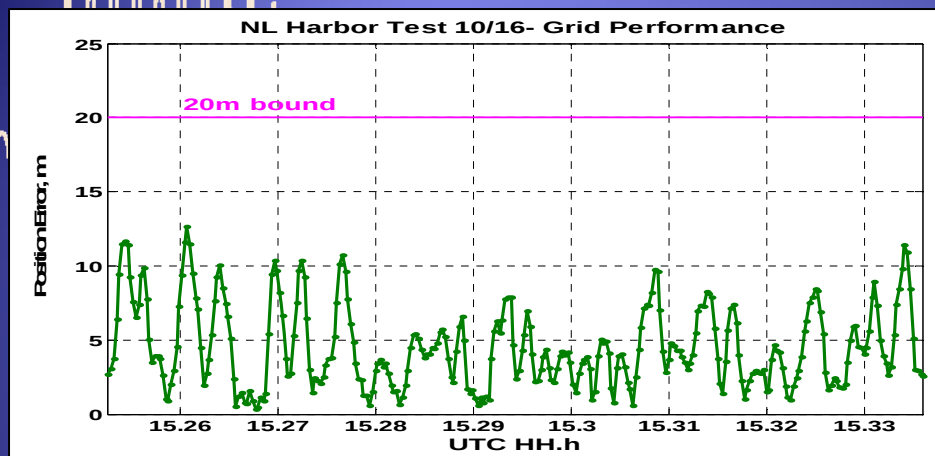


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Thames Performance



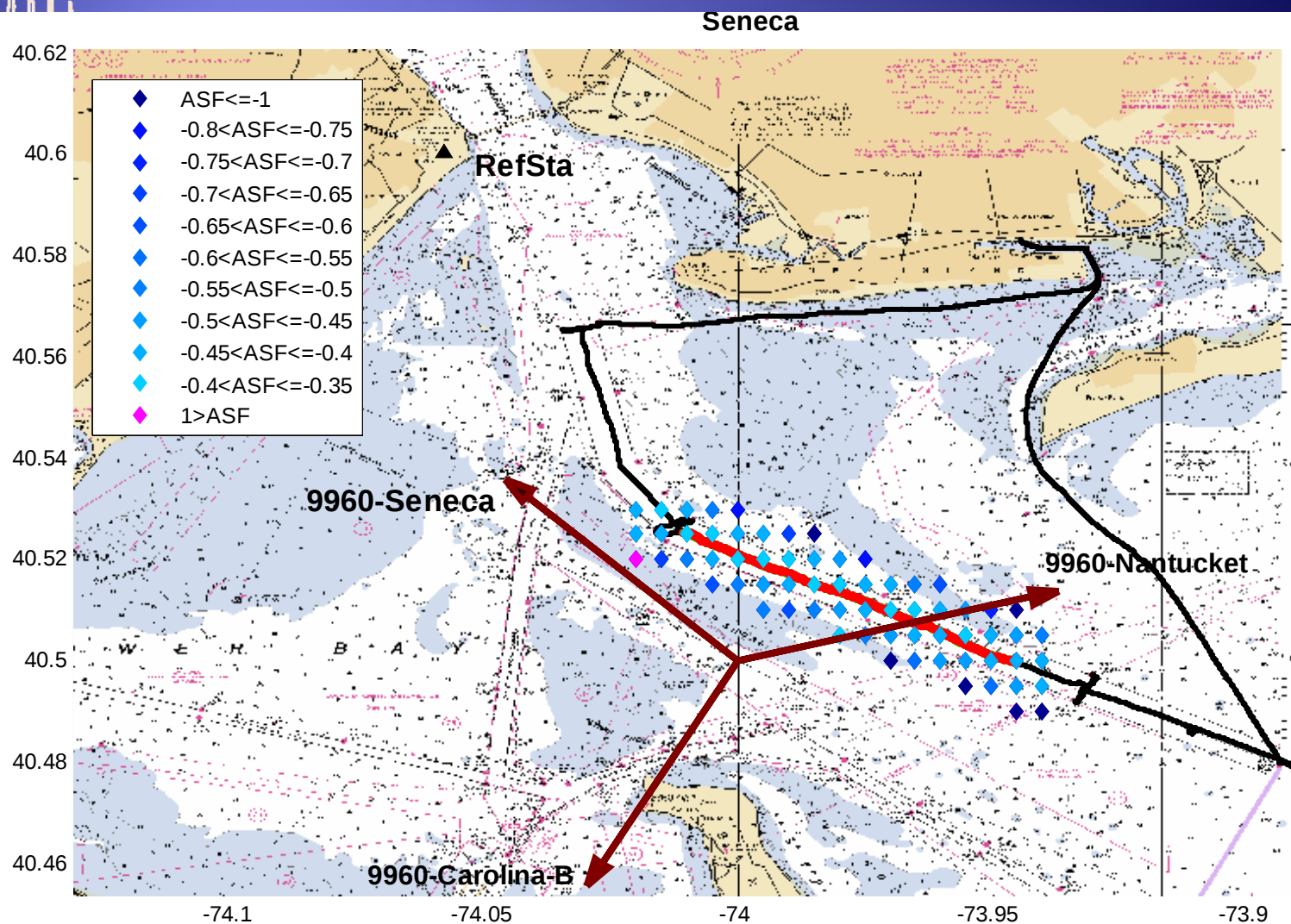
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New York Performance Example



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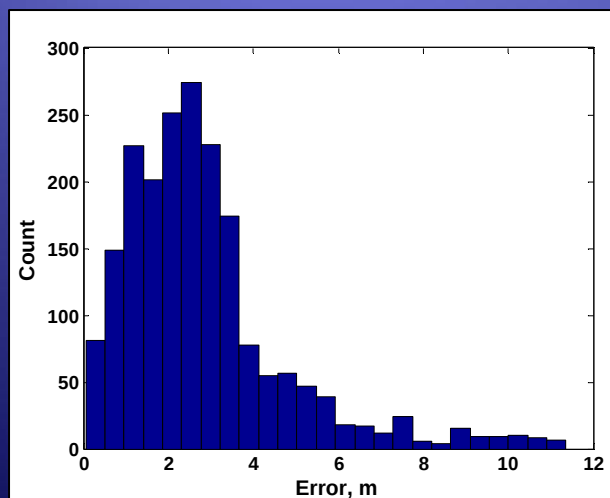
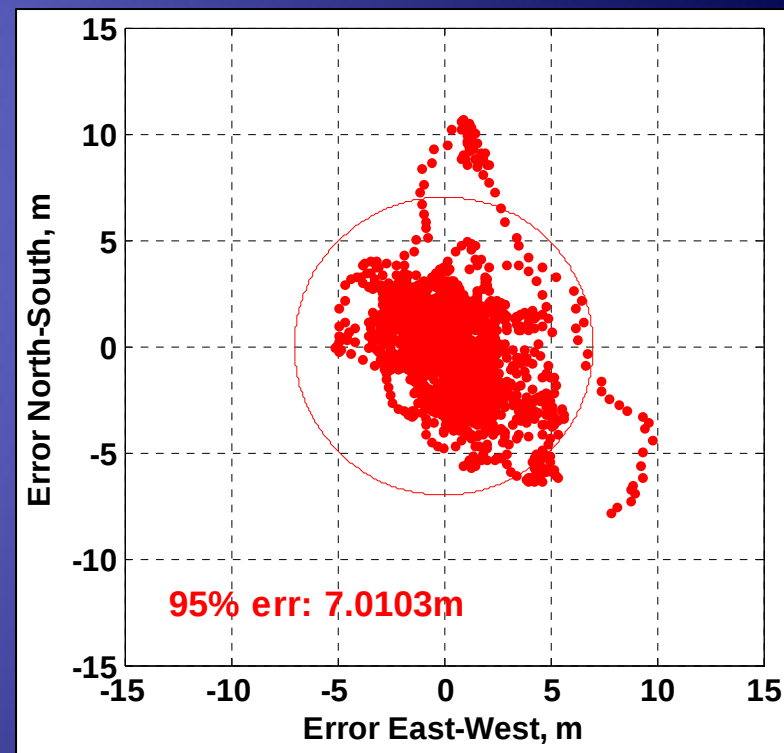
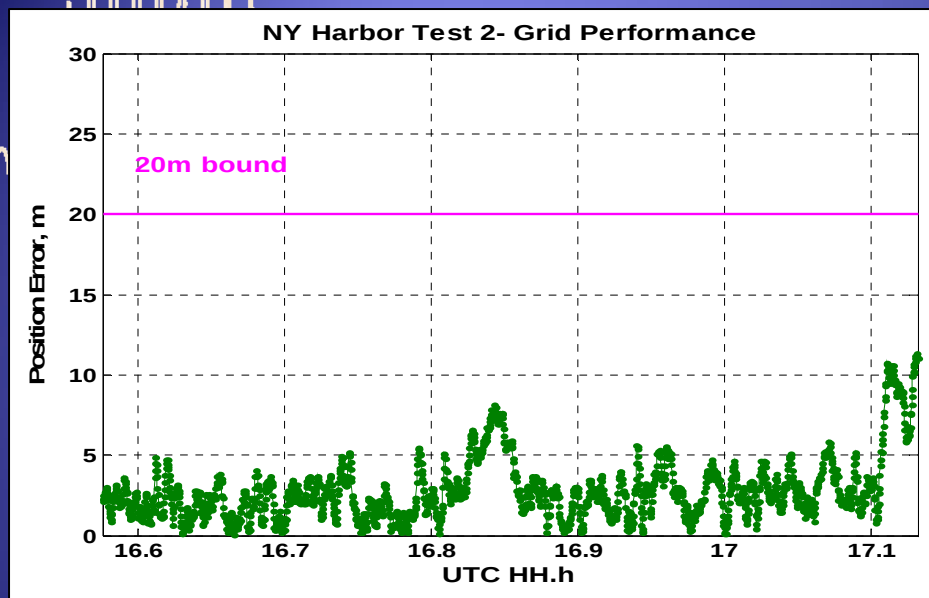
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NY Performance – Error Dist.



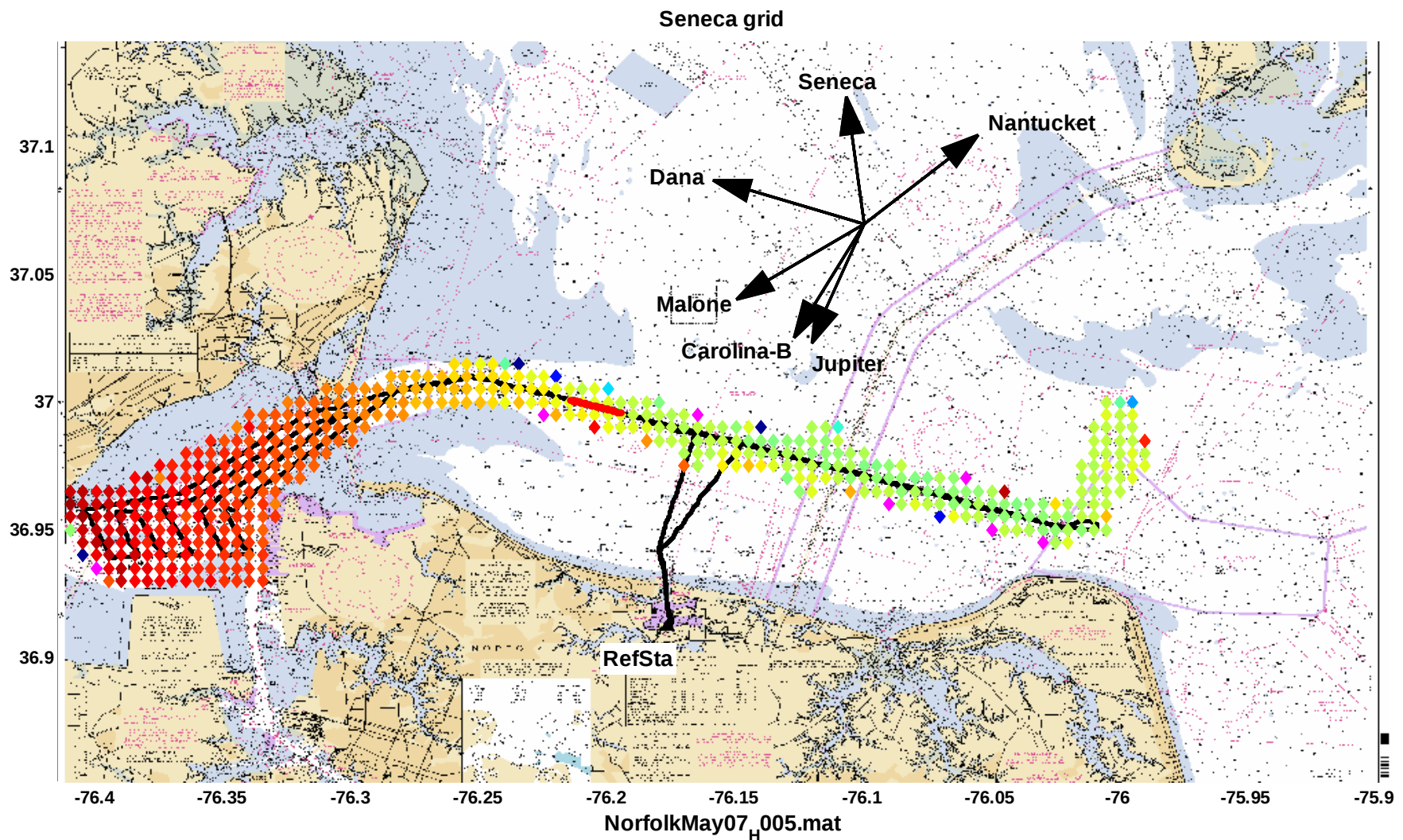
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Norfolk Performance Example



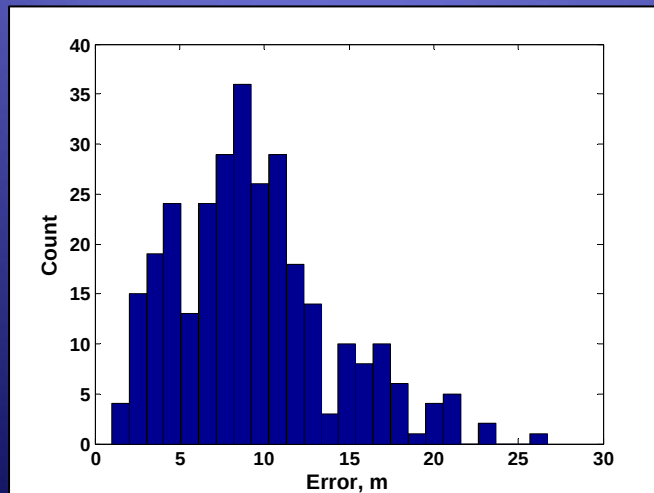
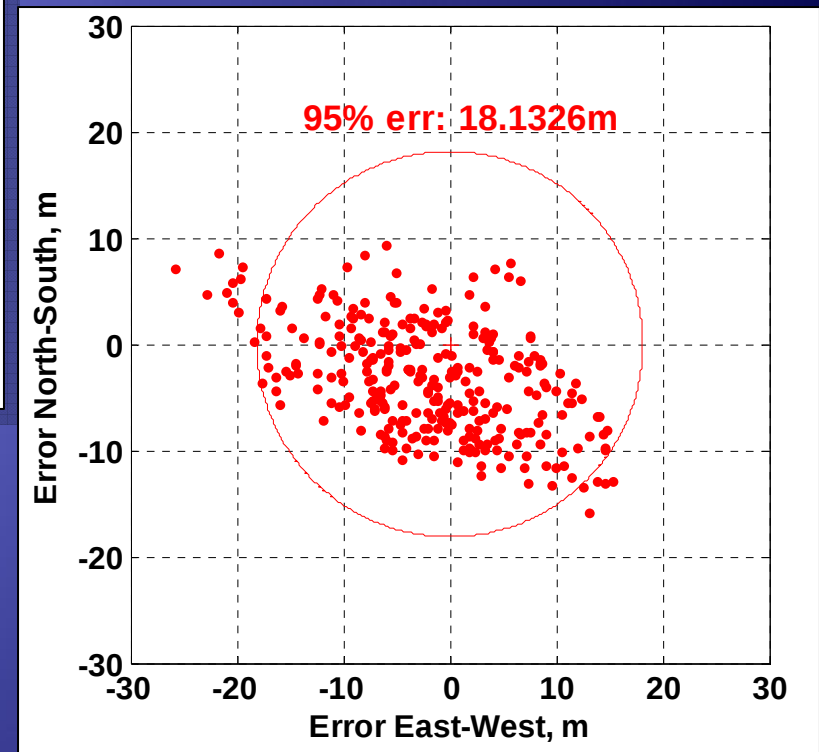
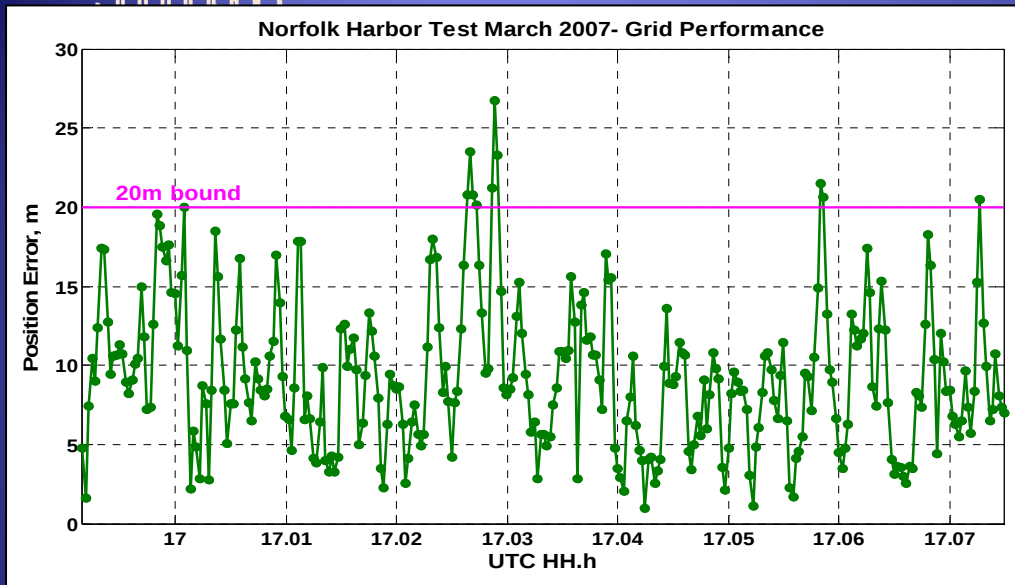
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Norfolk Performance – Error Dist.



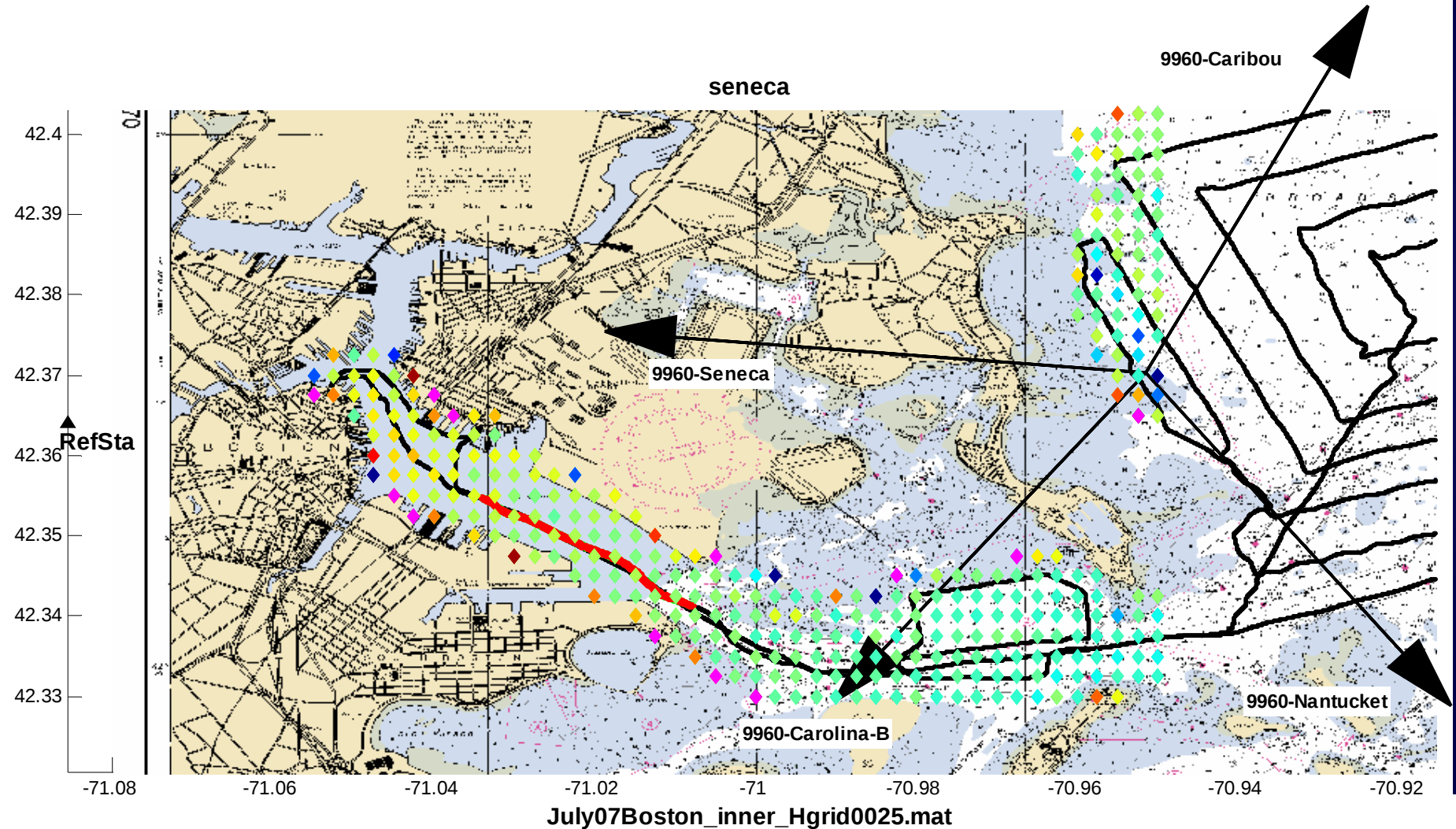
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Boston Performance Example



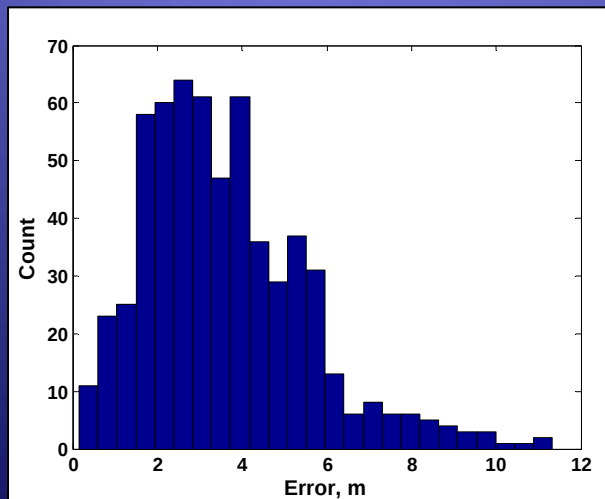
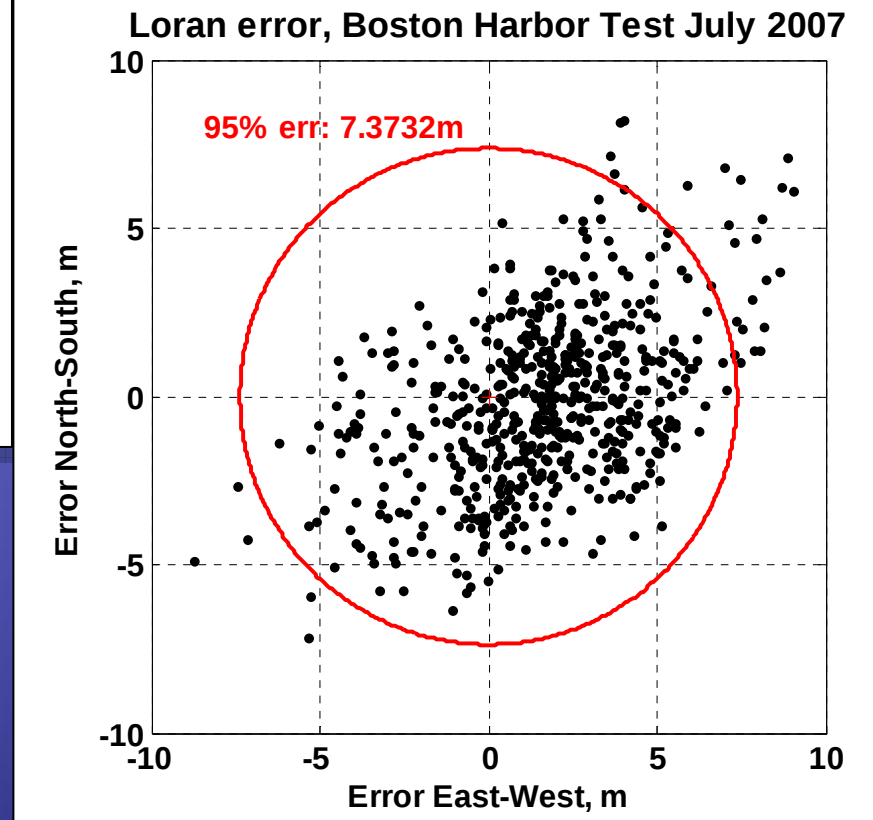
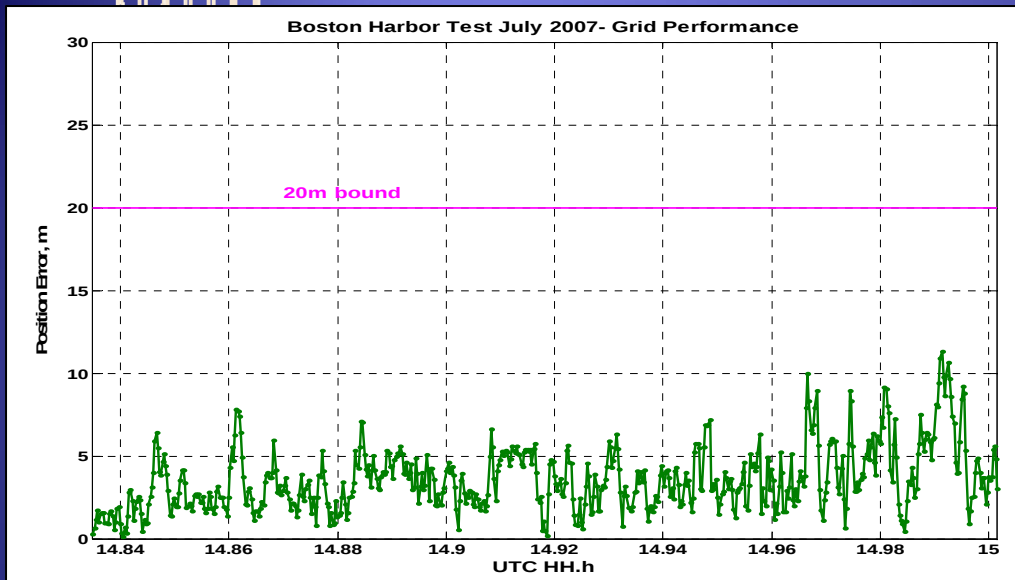
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Boston Performance – Error Dist.



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Temporal Corrections

- LDC Architecture
- Typical Spatial Correlation



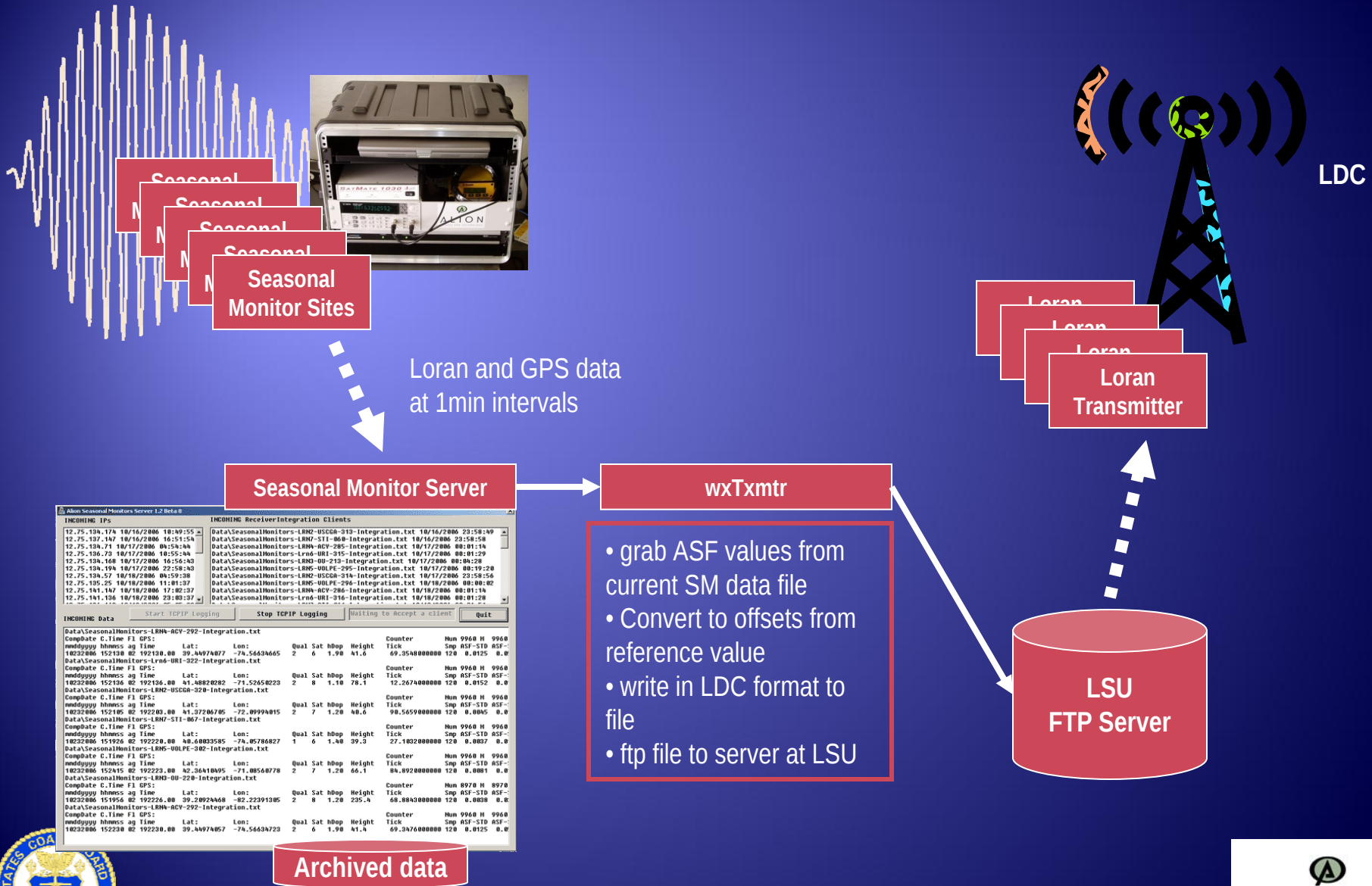
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LDC Architecture



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Typical LDC Message Sequence



- ◆ Each message is 45 bits and takes 24 symbols to transmit at 1 symbol/group
- ◆ At 8970 takes 2.15sec/msg
- ◆ Time: 5 every 64 messages or ~ every 27.5sec
- ◆ ASF data repeats every 2.3 min



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eLoran Performance

- Prototype receiver
- Sample performance



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- TOAs
- demodulated LDC symbols
- real-time ASFs (for comparison)

- Lookup ASF grid value
- RS decode LDC symbols,
- Interpret transmitted data
- Apply transmitted temporal correction and reference station value
- Calculate position solution
- Output position as NMEA string



- Display position tracks of eLoran, Loran, and GPS systems

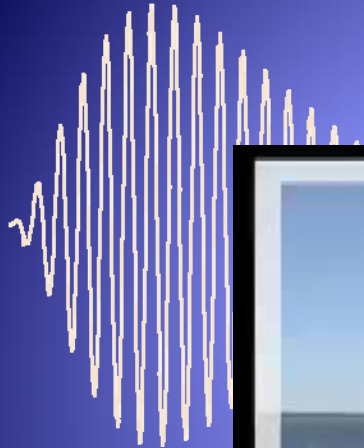
- Loran position

NovAtel Receiver

- GPS position



eLoran Results on the Thames



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Conclusions

◆ Spatial ASF Grids

- ◆ Noise in the ASF measurements gets averaged out by the grid creation process
- ◆ 500m grid spacing is typically sufficient
 - ◆ Smaller spacing only if dictated by physical size of HEA
 - ◆ Smaller sizes just chase the noise in the measurements
- ◆ Harbor Survey procedure has been established and proven

◆ Temporal ASF

- ◆ Correct temporal value is critical to meeting HEA accuracy
- ◆ Currently under investigation:
 - ◆ Frequency (and filtering) of corrections
 - ◆ Monitor site spacing
 - ◆ End-state distribution architecture

◆ eLoran Receiver

- ◆ In areas where geometry / signal strength are poor, receiver performance becomes critical
- ◆ <20m real-time is difficult – even with ASF spatial (grid) and temporal corrections, requires a good receiver



Acknowledgements

◆ Alion New London Team

- ◆ Christian Oates
- ◆ Ruslan Shalaev
- ◆ Mark Wiggins
- ◆ Ken Dykstra

◆ USCG Auxiliary

- ◆ Captain and crew of Launch #5 (New York)
- ◆ Captain and crew of Myst (New London)
- ◆ Captain and crew of Halcyon Lace (Norfolk)
- ◆ Captain and crew of Three J's (Boston)

◆ USCG Loran Support Unit

- ◆ CDR Chris Nichols
- ◆ LT Chris Dufresne



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Questions?

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